Artificial Cognitive Systems

Module 3: Cognitive Architectures

Lecture 1: The role of a cognitive architecture; desirable characteristics; core cognitive abilities; how to design a cognitive architecture

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What are the characteristics of a cognitive agent?

The chief characteristic of a cognitive agent is the ability to act effectively in a world that is uncertain, under-specified, dynamic, possibly cooperating with other cognitive agents

To achieve goals adaptively and robustly in these circumstances requires a complex system that can

- Construct models of the way the world works,
- Use them to guide actions prospectively, and
- Update them dynamically as the system continually learns through its interactions

A cognitive architecture is the way we specify what is required to achieve this.

What is a cognitive architecture?

A cognitive architecture is a software framework that integrates all the elements required for a system to exhibit the characteristic attributes of a cognitive agent

The design of a cognitive architecture requires the specification of the formalisms

for all the processes and knowledge representations used by that framework

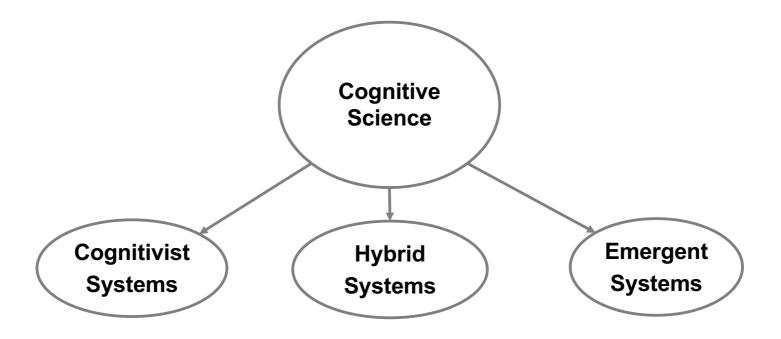
How does a cognitive architecture work?

A cognitive architecture integrates the core cognitive abilities so that these abilities can be dynamically coordinated

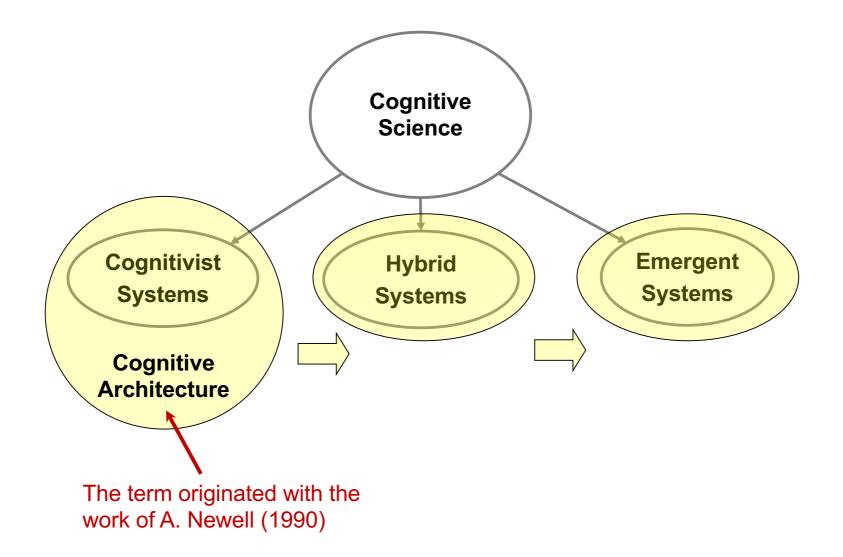
Allowing the agent to exhibit flexible context-sensitive behaviour, prospectively selecting and controlling the actions that are required to achieve given goals

A cognitive architecture should also be able to develop autonomously so that its performance improves over time with experience

Perception
Attention
Action selection
Memory
Learning
Reasoning
Meta-reasoning
Prospection



There are three paradigms of cognitive science



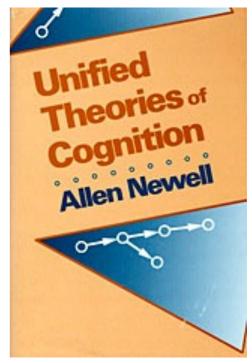
Attempts to create Unified Theories of Cognition (UTC)

UTCs cover a broad range of cognitive issues

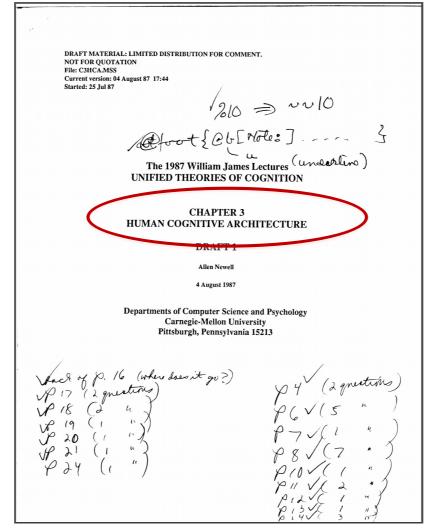
- Attention
- Memory
- Problem solving
- Decision making
- Learning

from several aspects

- Psychology
- Neuroscience
- Computer Science



https://www.hup.harvard.edu/catalog.php?isbn=9780674921016



http://digitalcollections.library.cmu.edu/awweb/awarchive?type=file&item=352120

An encapsulation of a **scientific hypothesis** about those aspects of **human cognition** that are:

- relatively constant over time and
- relatively independent of task

(Ritter & Young 2001)

- Generic computational model:
 - Not domain-specific
 - Not task-specific
- Knowledge provides the required specificity:

Cognitive Architecture + Knowledge = Cognitive Model

- Lehman et al. (1998) put it slightly differently:

BEHAVIOR = ARCHITECTURE x CONTENT

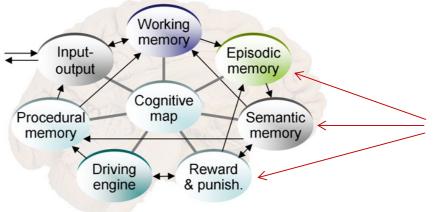
Knowledge is typically:

- Determined by the designer (explicitly or implicitly)
- Adapted and augmented by machine learning techniques

Overall structure and organization of a cognitive system

- Essential Modules
- Essential relations between these modules
- Essential algorithmic and representational details in each module

(Sun 2007)



Commitment to formalisms for representation and processes

(Langley 2005, Langley 2006, Langley et al. 2009)

(GMU-BICA Architecture: Samsonovich 2005)

Commitment to formalisms for

- Short-term & long-term memories that store the agent's beliefs, goals, and knowledge
- Representation & organization of structures embedded in memory
- Functional processes that operate on these structures
 - Performance / utilization
 - Learning
- Programming language to construct systems embodying the architectures assumptions

(Langley 05, Langley 06, Langley et al. 09)

Emergent approaches focus on development

- From a primitive state
- To fully cognitive state, over the system's lifetime



https://childmaltreatmentresearchblog.wordpress.com/about/

- Two different views of development
 - Individual
 - Social
- Two different theories of cognitive development



Jean Piaget 1896-1980

https://en.wikipedia.org/wiki/Jean_Piaget



Lev Vygotsky 1896-1934

https://en.wikipedia.org/wiki/Lev_Vygotsky

The cognitive architecture is the system's phylogenetic configuration

- The basis for ontogenesis: growth and development
 - Innate skills
 - Core knowledge (cf. Spelke)
- A structure in which to embed mechanisms for
 - Perception
 - Action
 - Adaptation
 - Anticipation
 - Motivation
 - ... Development of all these

Strong focus on

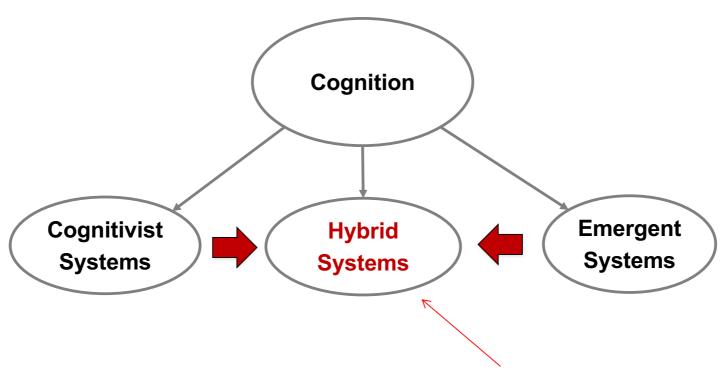
- Autonomy-preserving, anticipatory, adaptive skill construction
- The morphology of the physical body in which the architecture is embedded

The emergent approach rejects:

- Dualism between mind and body
- Functionalism that treats cognitive mechanisms independently of the physical platform
 - Computational functionalism
 - Robotic functionalism

Ziemke, T., The body of knowledge: On the role of the living body in grounding embodied cognition. BioSystems (2016), http://dx.doi.org/10.1016/j.biosystems.2016.08.005

Hybrid Cognitive Architecture



Symbolic & sub-symbolic representation and computational processing (i.e. h,not H)

- Realism
- Behavioral Characteristics
- Cognitive Characteristics
- Functional Capabilities
- Development
- Dynamics

PHILOSOPHICAL PSYCHOLOGY, VOL. 17, NO. 3, SEPTEMBER 2004



Desiderata for cognitive architectures

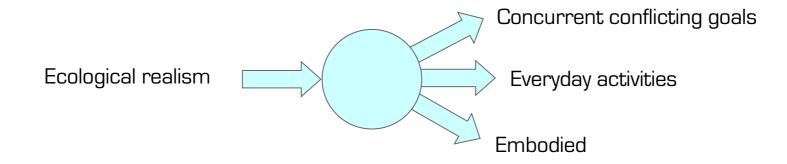
Ron Sun

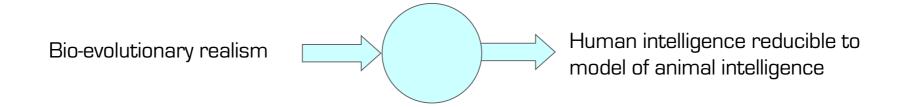
(Langley et al. 2009, Sun 2007)

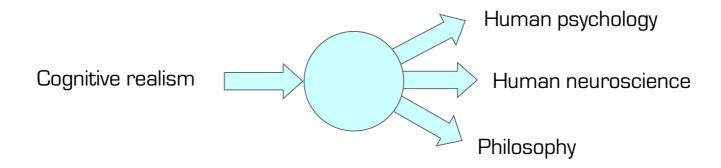
(Krichmar & Edelman 2006, 2007; Vernon et al. 2016)

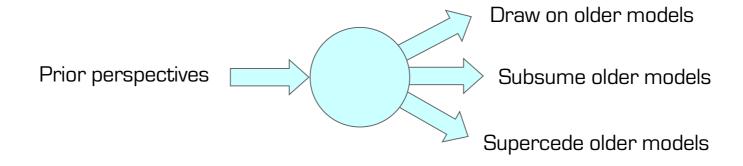
Realism (Sun 2004):

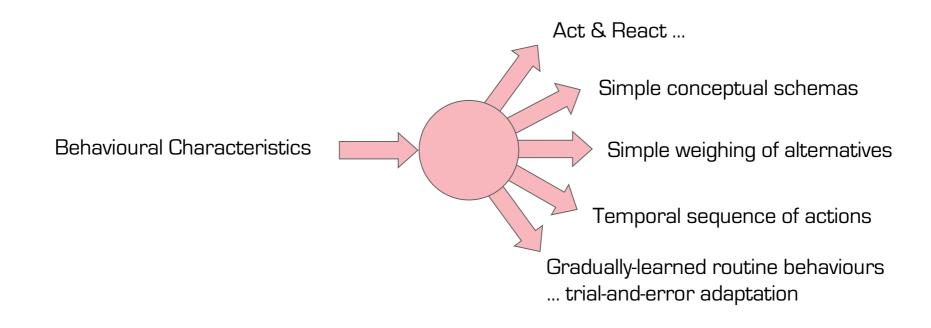
- 1. Ecological realism
- 2. Bio-evolutionary realism
- 3. Cognitive realism
- 4. Inclusiveness of prior perspectives











(Sun 2004)

Cognitive Characteristics

Explicit symbolic learning

Functional or physical modularity

(Sun 2004)

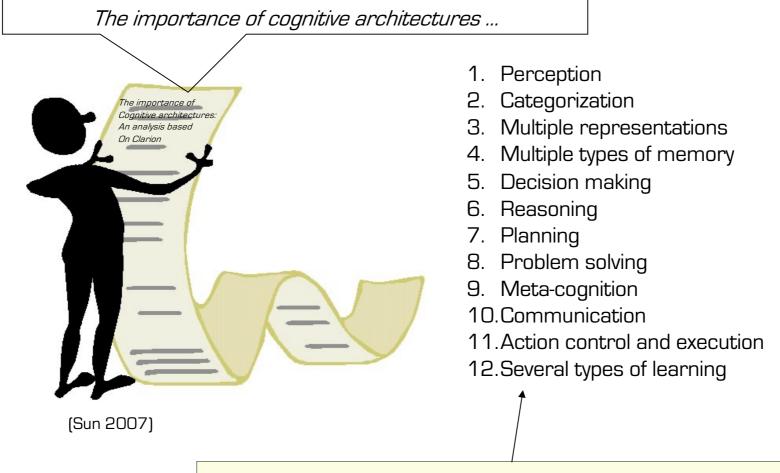
Implicit bottom-up learning

Cognitive architectures: Research issues and challenges



(Langley et al. 2009)

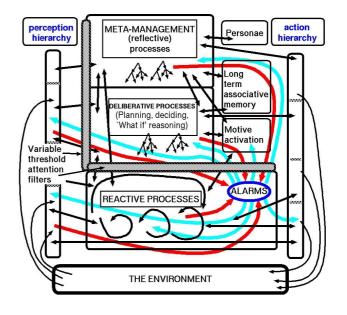
- 1. Recognition & categorization
- 2. Decision-making & choice
- 3. Perception & situation assessment
- 4. Prediction & monitoring
- 5. Problem solving & planning
- 6. Reasoning & belief maintenance
- 7. Execution & action
- 8. Interaction & communication
- 9. Remembering, reflection, & learning



The importance of the interconnectivity between these processes

Perception	Central Processing	Action
	Meta-management (reflective processes) (newest)	
	Deliberative reasoning ("what if" mechanisms) (older)	
	Reactive mechanisms (oldest)	

Cogaff Cognitive Architecture Schema (Sloman 2000)



H-Cogaff Cognitive Architecture (Sloman 2001)

Development

Cognitive Architectures of Developmental Systems (Krichmar & Edelman 2005, 2006)

- 1. Address connectivity and interaction between circuits/regions in the brain
- 2. Effect perceptual categorization, without a priori knowledge (a model generator, rather than a model fitter, cf (Weng 04))
- 3. Embodied & capable of exploration
- 4. Minimal set of innate behaviours
- 5. Value system (set of motivations) to govern development

PHILOSOPHICAL PSYCHOLOGY, VOL. 17, NO. 3, SEPTEMBER 2004



Desiderata for cognitive architectures

Ron Sun



Biologically Inspired Cognitive Architectures

Volume 18, October 2016, Pages 116-127



Research article

Desiderata for developmental cognitive architectures

David Vernon^{a.} ♣ · ➡, Claes von Hofsten^b, Luciano Fadiga^{c. d}

Bhow more

http://dx.doi.org/10.1016/j.bica.2016.10.004

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Desideratum 1. Value systems and motives

Desideratum 2. Physical embodiment

Desideratum 3. Sensorimotor contingencies

Desideratum 4. Perception

Desideratum 5. Attention

Desideratum 6. Prospective action

Desideratum 7. Declarative and procedural memory

Desideratum 8. Multiple modes of learning

Desideratum 9. Internal simulation

Desideratum 10. Constitutive autonomy



Biologically Inspired Cognitive Architectures

Volume 18, October 2016, Pages 116-127



Research article

Desiderata for developmental cognitive architectures

David Vernon^{a, ≜ ⋅ ™}, Claes von Hofsten^b, Luciano Fadiga^{c, d}

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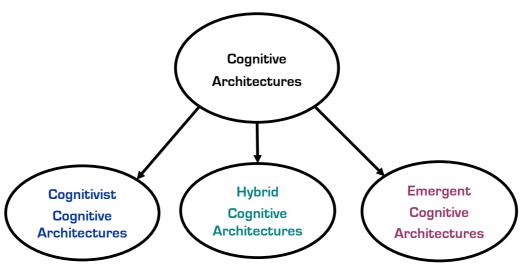
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Facets of a Cognitive Architecture

- Component functionality
- Component interconnectivity
- System dynamics

Organizational decomposition

- Explicit inter-connectivity
- Representational formalism
- Algorithmic formalism



Framework in which to embed knowledge

- Memories
- Formalisms for learning
- Programming mechanism

Phylogeny - basis for development

- Innate skills & core knowledge
- Memories
- Formalism for autonomy
- Formalism for development

Core Cognitive Abilities

- 1. Perception
- 2. Attention
- 3. Action selection
- 4. Memory
- 5. Learning
- 6. Reasoning
- 7. Metacognition
- 8. Prospection

I. Kotseruba and J. Tsotsos. 40 years of cognitive architectures: core cognitive abilities and practical applications. Artificial Intelligence Review, Vol. 53, No. 1, pp. 17-94, 2020.

Not included in (Kotseruba and Tsotsos 2020)

- 1. Perception
- 2. Attention
- 3. Action selection
- 4. Memory
- 5. Learning
- 6. Reasoning
- 7. Metacognition
- 8. Prospection

Makes use of many sensory modalities, e.g. vision, audition, and haptic (tactile and kinesthetic)

Perception transforms raw input into the system's internal representation

- 1. Perception
- 2. Attention
- 3. Action selection
- 4. Memory
- 5. Learning
- 6. Reasoning
- 7. Metacognition
- 8. Prospection

Reduces the information a cognitive system has to process by selecting relevant information & filtering out irrelevant information

Selective mechanisms

Choose one entity from many, e.g. gaze & viewpoint

Restrictive mechanisms

Choose some entities from many:

Priming what to look for or where to look for it

Suppressive mechanisms

Suppress some entities from many

i.e. features, objects, or locations that are not relevant

(Kotseruba and Tsotsos 2018)

- 1. Perception
- 2. Attention
- 3. Action selection
- 4. Memory
- 5. Learning
- 6. Reasoning
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Determines what the agent should do next

Planning

Determines a sequence of steps to read a certain goal prior to execution of the plan

Dynamic action selection

Selection of one action based on knowledge at the time, typically using winner-take-all, probabilistic, or pre-defined order selection mechanisms

- 1. Perception
- 2. Attention
- 3. Action selection
- 4. Memory
- 5. Learning
- 6. Reasoning
- 7. Metacognition
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Kotseruba and Tsotsos identify six types of memory

Short-term sensory memory
Short-term working memory
Long-term episodic memory
Long-term semantic memory
Long-term procedural memory
Long-term global memory

recent percepts
information relevant to current task
key to anticipation; autobiographical
general knowledge about the world
motor skills
for architectures that don't draw a
type-duration distinction:

- 1. Perception
- 2. Attention
- 3. Action selection
- 4. Memory
- 5. Learning
- 6. Reasoning
- 7. Metacognition
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The ability of a system to improve performance over time through the acquisition of knowledge or skill

Declarative learning ...
Non-declarative learning ...

explicit knowledge acquisition . perceptual, procedural, associative,

non-associative learning

Supervised learning
Unsupervised learning
Reinforcement learning

- 1. Perception
- 2. Attention
- 3. Action selection
- 4. Memory
- 5. Learning
- 6. Reasoning
- 7. Metacognition
- 8. Prospection

The ability to logically and systematically process knowledge, typically to infer conclusions

Three classical forms of logical inference: deduction, induction, abduction

Reasoning focusses on the practical objective of finding the next (best) action to perform

- 1. Perception
- 2. Attention
- 3. Action selection
- 4. Memory
- 5. Learning
- 6. Reasoning
- 7. Metacognition
- 8. Prospection

Metacognition refers to the ability of a cognitive system has to monitor its internal cognitive processes, reason about them, and adapt them

Metacognition is needed for social cognition if the agent is to form a theory of mind, also known as perspective-taking, i.e. the ability to infer the cognitive states of other agents with which it is interacting

- 1. Perception
- 2. Attention
- 3. Action selection
- 4. Memory
- 5. Learning
- 6. Reasoning
- 7. Metacognition
- 8. Prospection

Prospection – the capacity to anticipate the future – is one of the hallmark attributes of cognition

It lies at the heart of the other core characteristics of a cognitive agent: autonomy, perception, action, learning, and adaptation

[Vernon 2014]

It is central to action since actions are goal-directed and guided by prospective information

[von Hofsten 2009]

Internal simulation plays a key role in prospection

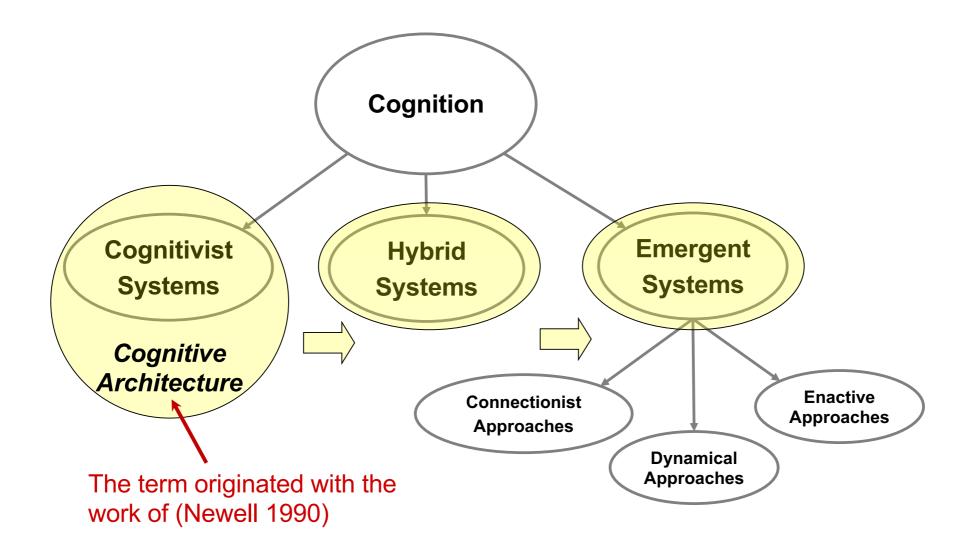
How to Design A Cognitive Architecture

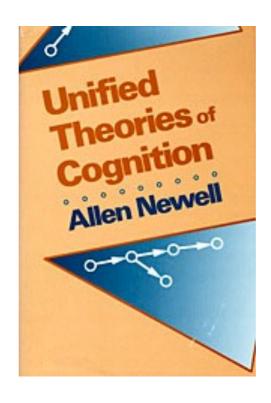
D. Vernon. "Two Ways (Not) To Design a Cognitive Architecture", Proceedings of EUCognition 2016, Cognitive Robot Architectures, European Society for Cognitive Systems, Vienna, 8-9 December, 2016, R. Chrisley. V. C. Müller, Y. Sandamirskaya. M. Vincze (eds.), CEUR-WS Vol-1855, ISSN 1613-0073, pp. 42-43.

There are **two** reasons that people work in cognitive system

1. They want smart systems, e.g. robots

2. They want to understand cognition





"all aspects, all perspectives"







Go for what's desirable:

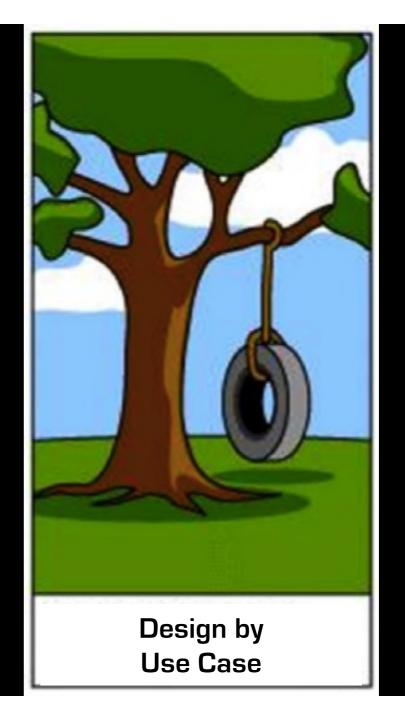
desiderata

Clarify the explanation: use cases











LEA Robot Care Systems

MOBILITY PROBLEMS

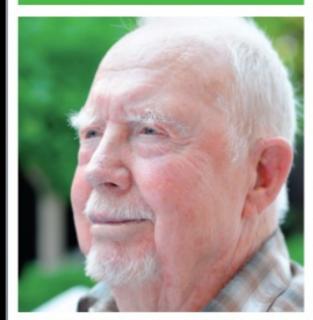
General weakness of muscles and stiffness for which the elderly uses stroller support

COGNITIVE PROBLEMS

Mild perceptive and cognitive impairment (e.g. impaired hearing, seeing, scent, as well as forgetfulness due to aging)

TREMOR

Tremor in arm muscles due to which elderly have trouble lifting or/and carrying objects



Mr Tucker (82) is suffering from hip injury



Mrs Baker (85) is suffering from dementia



Mrs Janssen (83) is suffering from tremor

LEA from Robot Care Systems





USE CASES TWO SCENARIOS

Use cases for single user at home

Use case ADL 1: Personal hygiene and grooming

Use case ADL 2: Eating and drinking

Use case ADL 3: Continence

Use case ADL 4: Personal assistant (reminders)

Use case ADL 5: Functional transfers

Use case ADL 6: Exercises

Use case ADL 7: Communication via internet

Use case ADL 8: Remote care (additional

functionality)

Use cases for elderly living in care centres

Use case ADL 1: Personal hygiene and grooming

Use case ADL 2: Eating and drinking

Use case ADL 3: Continence

Use case ADL 4: Personal assistant (reminders)

Use case ADL 5: Functional transfers

Use case ADL 6: Exercises

Use case ADL 7: Communication with family, caregivers

via internet

NO NAVIGATION FUNCTIONALITIES!!

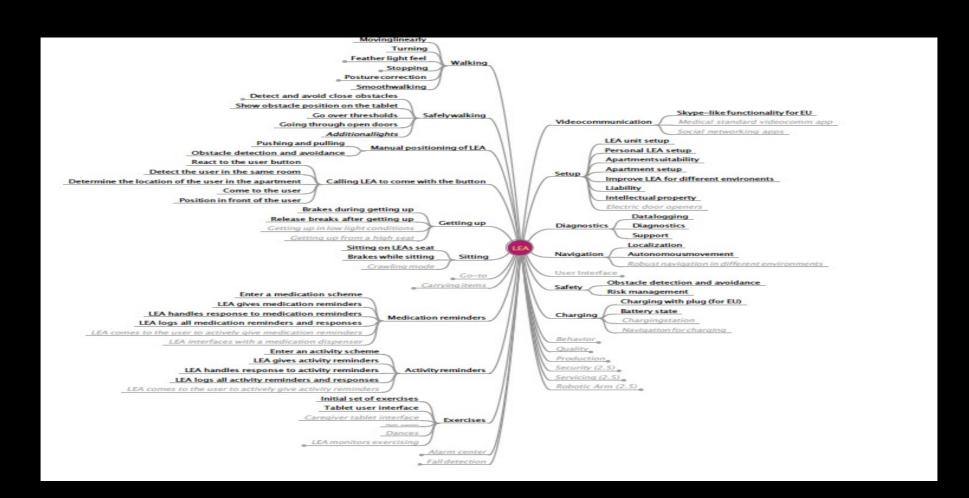




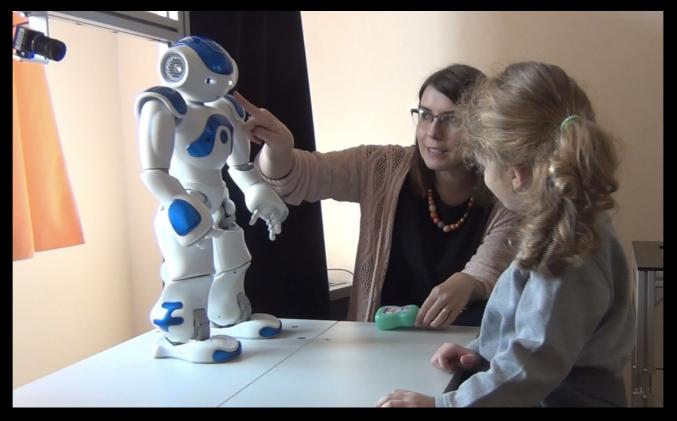








LEA from Robot Care Systems



Assisting in Psychotherapy with ASD Children (Simple Perspective Taking in Interaction Tasks)







D1.1 Intervention Definition

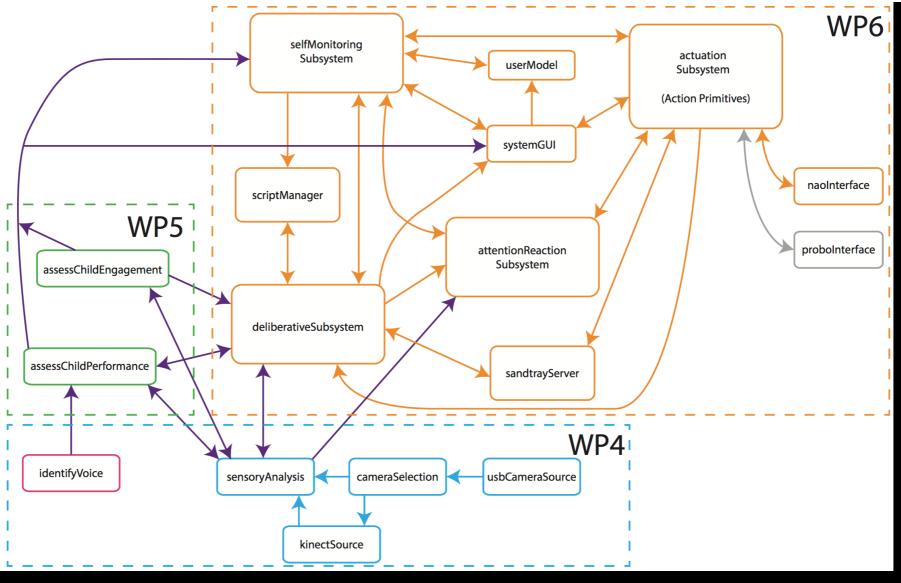
Joint attention

Look at a picture The robot looks at the picture/object to the left or right Dobject localization Move head to centre gaze on the picture Look back at child Look for a face UNTIL the child's face is detected Determine the location of the child Move head to look at the child Adjust body posture to face the child Check to see if the child is looking at the picture The robot stares at the picture/object for a specified time The robot stares at the picture/object for a specified time The robot stares at the picture/object for a specified time The robot stares at the picture/object for a specified time The robot stares at the picture/object for a specified time The robot stares at the picture/object for a specified time The child has to identify where the robot looked Move head to centre gaze on the child Move torso to face child and adjust gaze Compute child's head gaze Compute child's eye gaze (ideally) The child has to look at one of the objects	The actions defined in the intervention tasks	The component movements and sensory cues	The sensory-motor processes provide input for the definition of robot and child behaviour specification	The comments which add explanations of what is happening in the task at that point.
UNTIL the child's face is detected Determine the location of the child Move head to centre gaze on the child Move head to centre gaze on the child Move torso to face child and adjust gaze posture to face the child Check to see if the child is looking at the Determine the gaze direction of the child Compute child's head gaze	Look at a picture		Object localization	
	Look back at child	UNTIL the child's face is detected Determine the location of the child Move head to look at the child Adjust body	Face localization Move head to centre gaze on the child	The child has to identify where the robot looked
		Determine the gaze direction of the child		The child has to look at one of the objects







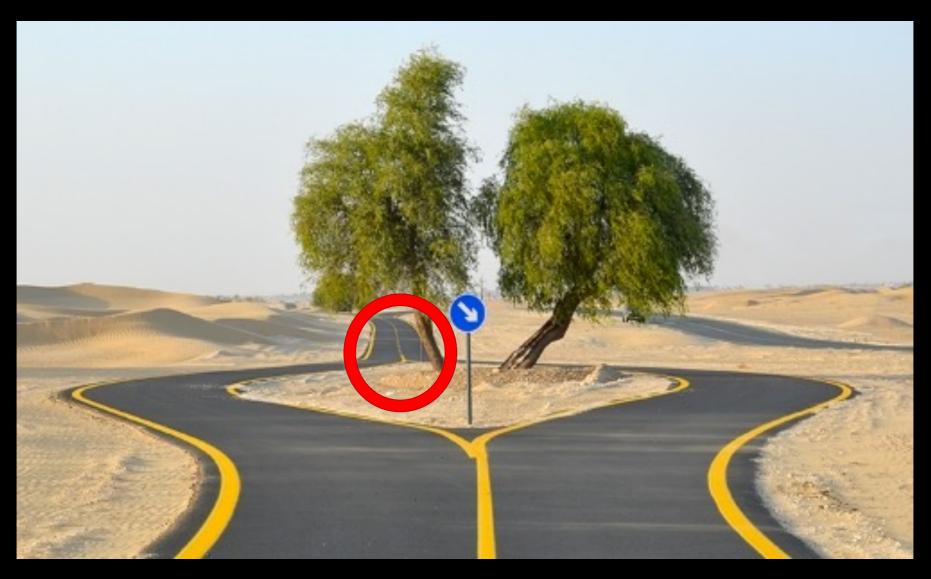






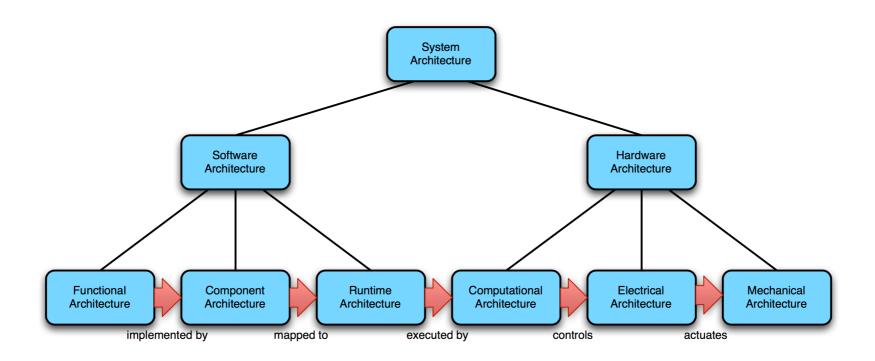


Design by Desiderata or Use Case



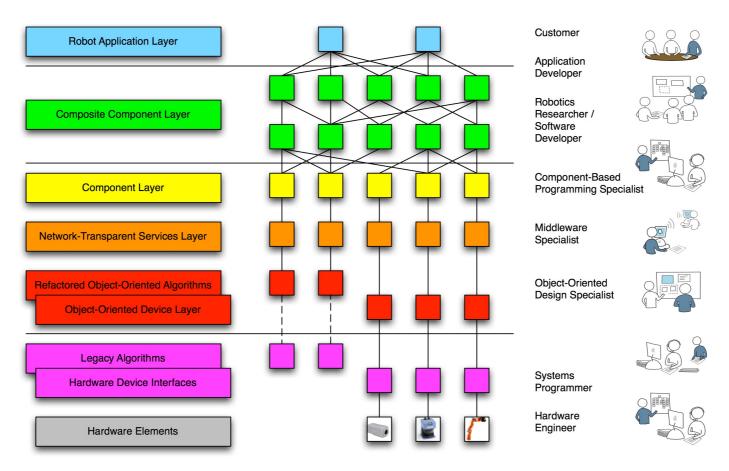
Design by Desiderata or Use Case

How to Design a Cognitive Architecture



G. Kraetzschmar, Software Engineering Factors for Cognitive Robotics, RockEU2 Robotics Coordination Action for Europe Two, Deliverable 3.5, 2017. https://www.eu-robotics.net/eurobotics/about/projects/rockeu2.html

How to Design a Cognitive Architecture



G. Kraetzschmar, Software Engineering Factors for Cognitive Robotics, RockEU2 Robotics Coordination Action for Europe Two, Deliverable 3.5, 2017. https://www.eu-robotics.net/eurobotics/about/projects/rockeu2.html

Reading

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Further Reading

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- D. Vernon, C. von Hofsten, and L. Fadiga, "Desiderata for Developmental Cognitive Architectures", Biologically Inspired Cognitive Architectures, Vol. 18, pp. 116-127, 2016.
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