

# Data Structures and Algorithms for Engineers

## Module 7: Graphs

### Lecture 3: Depth-First Search (DFS) traversal & Topological Sort

David Vernon  
Carnegie Mellon University Africa

vernon@cmu.edu  
www.vernon.eu

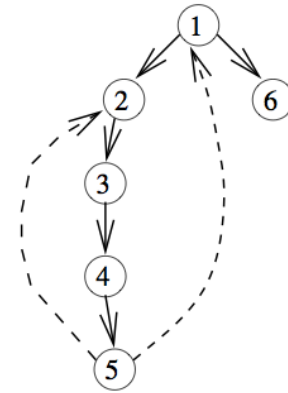
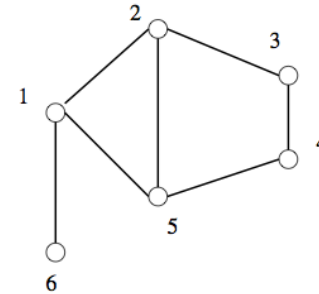
# Depth-First Search

- This implementation of DFS uses the idea of a **traversal time** for each vertex
- The clock ticks each time we **enter** or **exit** any vertex
- We keep track of the entry and exit time for each vertex
- These entry and exit times are useful in many applications of DFS (e.g., topological sort; see later)
  - `process_vertex_early()` ... take action on entry
  - `process_vertex_late()` ... take action on exit
- DFS uses a **stack** but we can avoid using an explicit stack if we use recursion

# Depth-First Search

- DFS partitions edges of an undirected graph into exactly two classes

- Tree edges
- Back edges



- **Tree edges** discover **new** vertices
  - Encoded in the `parent` relation
- **Back edges** link a vertex to an **ancestor** of the vertex being expanded

# Depth-First Search

```
DFS( $G, u$ )
   $state[u] = \text{"discovered"}$ 
  process vertex  $u$  if desired
   $entry[u] = time$ 
   $time = time + 1$ 
  for each  $v \in Adj[u]$  do
    process edge  $(u, v)$  if desired
    if  $state[v] = \text{"undiscovered"}$  then
       $p[v] = u$ 
      DFS( $G, v$ )
   $state[u] = \text{"processed"}$ 
   $exit[u] = time$ 
   $time = time + 1$ 
```

# Depth-First Search

```
/* Depth-First Search */  
  
dfs(graph *g, int v){  
  
    edgenode *p;          /* temporary pointer */  
    int y;                /* successor vertex */  
  
    if (finished) return; /* allow for search termination */  
  
    discovered[v] = TRUE;  
    time = time + 1;  
    entry_time[v] = time;  
  
    process_vertex_early(v);
```

# Depth-First Search

```
p = g->edges[v];
while (p != NULL) {
    y = p->y;
    if (discovered[y] == FALSE) {
        parent[y] = v;
        process_edge(v,y);    // not discovered: tree edge
        dfs(g,y);
    }
    else if ((!processed[y]) // discovered but not processed: back edge
            || (g->directed)) // discovered, possibly processed, but directed edge
            // also a back edge,
        process_edge(v,y);

    if (finished) return;
    p = p->next;
}

process_vertex_late(v);
time = time + 1;
exit_time[v] = time;

processed[v] = TRUE;
}
```

# Depth-First Search

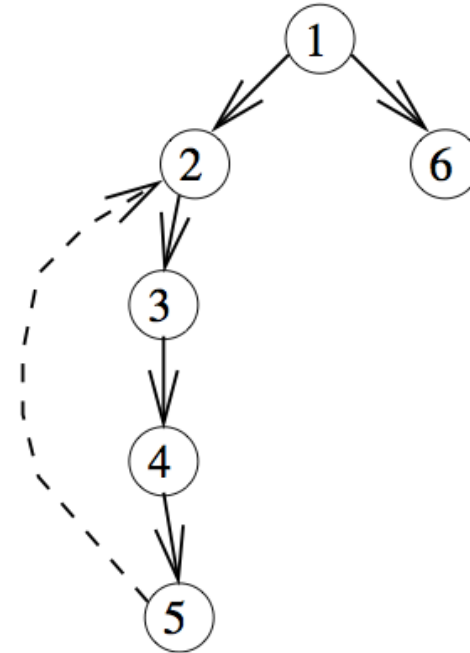
- Depth-First Search uses essentially the same idea as **backtracking**
  - Exhaustively searching all possibilities by advancing if it is possible
  - And backing up as soon as there is no unexplored possibility for further advancement
  - Both are most easily understood as recursive algorithms
- DFS **organizes** vertices by **entry/exit times**
- DFS **classifies** edges as either **tree edges** or **back edges**

# Depth-First Search

## Applications of Depth-First Search

### – Finding Cycles

- If there are no back edges, then all edges are tree edges and no cycles exist
- Finding a back edge identifies a cycle

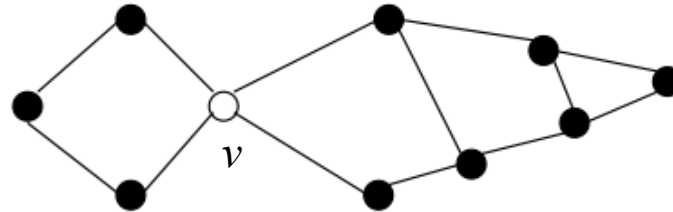




# Depth-First Search

## Applications of Depth-First Search

- Finding **Articulation Vertices** (also known as a **cut node**): weakest points in a graph/network

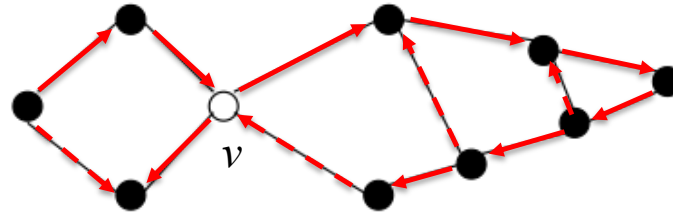


- $v$  is an articulation vertex if
  - $v$  is root of the DFS traversal tree and has 2 or more children, or
  - $v$  has a child  $s$  such that there is no back edge from  $s$  or any descendent of  $s$  to a proper ancestor of  $v$

# Depth-First Search

## Applications of Depth-First Search

- Finding **Articulation Vertices** (also known as a **cut node**): weakest points in a graph/network

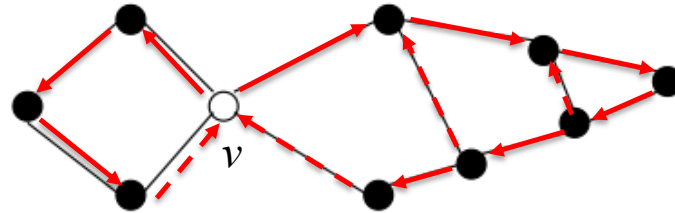


- $v$  is an articulation vertex if
  - $v$  is root of the DFS traversal tree & has 2 or more children, or
  - $v$  has a child  $s$  such that there is no back edge from  $s$  or any descendent of  $s$  to a proper ancestor of  $v$

# Depth-First Search

## Applications of Depth-First Search

- Finding **Articulation Vertices** (also known as a **cut node**): weakest points in a graph/network

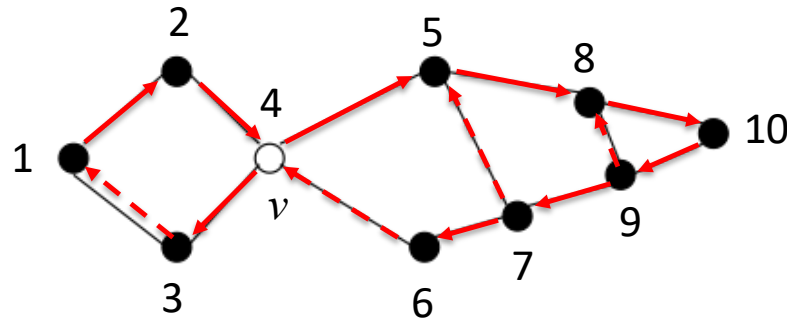


- $v$  is an articulation vertex if
  - $v$  is root of the DFS traversal tree & has 2 or more children, or
  - $v$  has a child  $s$  such that there is no back edge from  $s$  or any descendent of  $s$  to a proper ancestor of  $v$

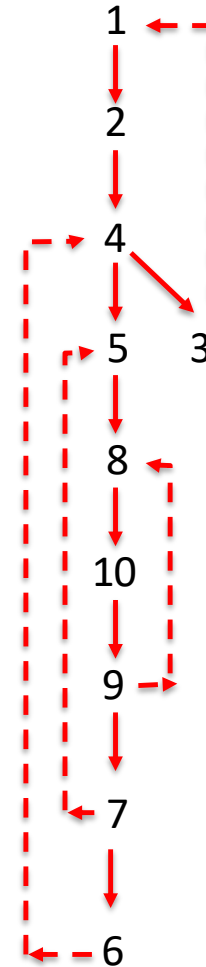
# Depth-First Search

## Applications of Depth-First Search

- Finding **Articulation Vertices** (also known as a **cut node**): weakest points in a graph/network



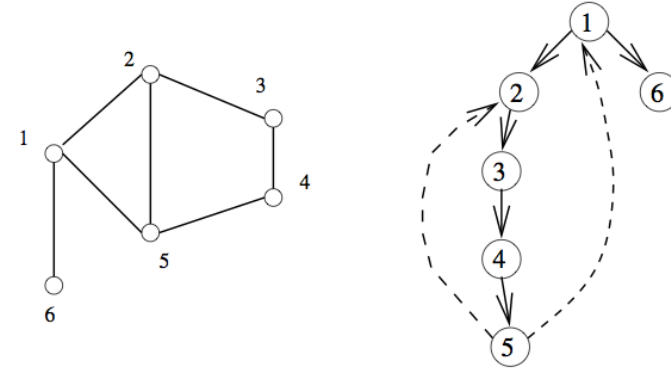
- $v$  is an articulation vertex if
  - $v$  is the root of the DFS traversal tree & has 2 or more children, or
  - $v$  has **any** child  $s$  such that there is no back edge from  $s$  or any descendent of  $s$  to a proper ancestor of  $v$
  - **No back edge from 5, 8, 10, 9, 7, 6 to 1, 2; so,  $v$  is an articulation vertex**



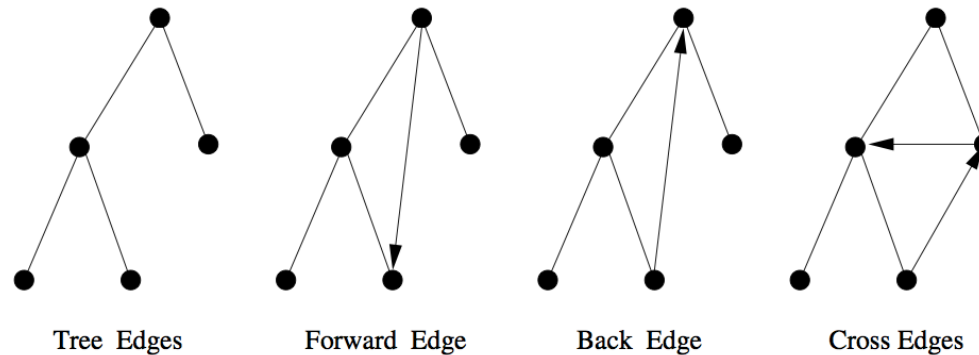
# Depth-First Search

## Depth-First Search on Directed Graphs

- When traversing **undirected** graphs, every edge is either in the depth-first search tree or it is a back edge to an ancestor in the tree



- For **directed** graphs, there are **4 depth-first search labellings**



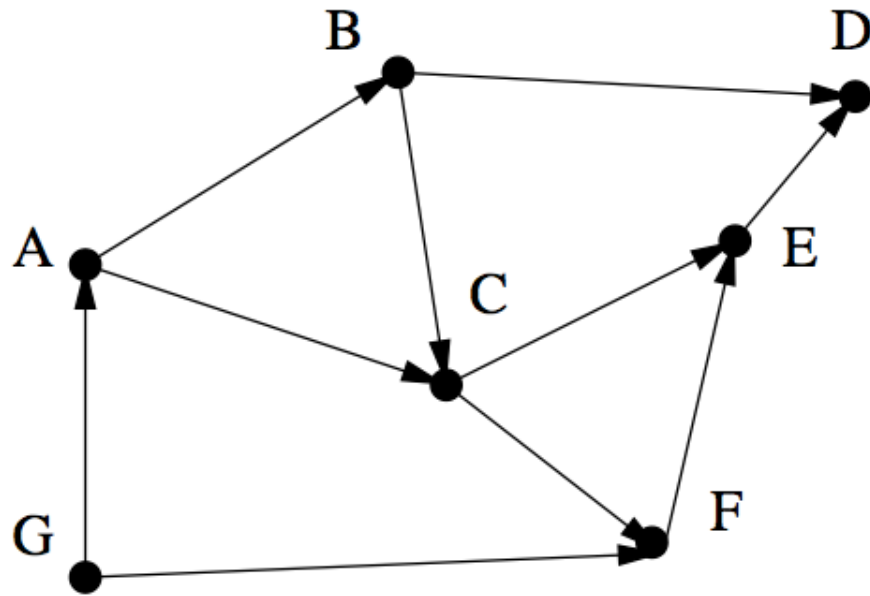
# Depth-First Search

```
int edge_classification(int x, int y){  
  
    /* if x is the parent of y, it's a tree edge */  
    if (parent[y] == x) return(TREE);  
  
    /* if y is discovered but not processed, this means we've */  
    /* already encountered on the traversal so it's a back edge */  
    if (discovered[y] && !processed[y]) return(BACK);  
  
    /* if y has been processed, and its entry time is greater than x's */  
    /* then it's a forward edge */  
    if (processed[y] && (entry_time[y]>entry_time[x])) return(FORWARD);  
  
    /* if y has been processed, and its entry time is less than x's */  
    /* then it's a cross edge */  
    if (processed[y] && (entry_time[y]<entry_time[x])) return(CROSS);  
  
    /* otherwise we have an invalid condition and it's unclassified. */  
    printf("Warning: unclassified edge (%d,%d)\n",x,y);  
}
```

# Topological Sorting

- The most important operation on **directed acyclic graphs (DAGs)**
- It orders the vertices on a line such that all directed edges go from left to right
  - Not possible if the graph contains a directed cycle
  - **It provides an ordering to process each vertex before any of its successors**
  - E.g., **edges represent precedence constraints**, such that the edge  $(x, y)$  means **job  $x$  must be done before job  $y$**
  - Any topological sort defines a valid schedule
- Each DAG has at least one topological sort

# Topological Sorting



A DAG with only one topological sort  $(G, A, B, C, F, E, D)$



# Topological Sorting

- Topological sorting can be performed using DFS
- A directed graph is a DAG iff there are no back edges
- Labelling the vertices in the **reverse order** in which they are *processed* (**completed**) finds the topological sort of a DAG

# Topological Sorting

Why? Consider what happens to each directed edge  $(x, y)$  as we encounter it exploring **vertex  $x$**

- If  $y$  is **currently undiscovered**, then **we start a DFS of  $y$  before we can continue with  $x$** . Thus  $y$  is marked processed/completed before  $x$  is, and  $x$  appears before  $y$  in the topological order
- If  $y$  is **discovered but not processed/completed**, then  $(x, y)$  is a back edge, which is forbidden in a DAG
- If  $y$  is **processed/completed**, then it will have been so labeled before  $x$ . Therefore,  $x$  appears before  $y$  in the topological order

# Topological Sorting

```
process_vertex_late(int v){
    push(&sorted,v);    // explicit stack for the sorted vertices
}

process_edge(int x, int y){

    int class;          /* edge class */

    class = edge_classification(x,y);

    if (class == BACK)
        printf("Warning: directed cycle found, not a DAG\n");
}
```

# Topological Sorting

```
/* Perform topological sort by doing a DFS on the graph,          */
/* pushing each vertex on a stack as soon as we have evaluated    */
/* all outgoing edges.                                           */
/* The top vertex on the stack always has no incoming edges from any */
/* vertex on the stack.                                           */
/* After the DFS, repeatedly popping the vertices from the stack   */
/* yields a topological ordering                                   */

topsort(graph *g) {

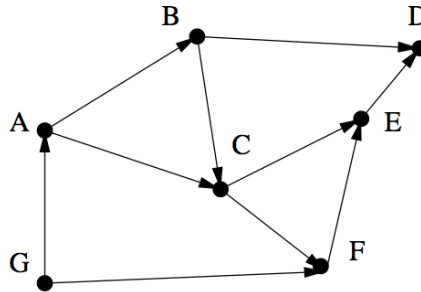
    int i;

    init_stack(&sorted);

    for (i=1; i<=g->nvertices; i++)
        if (discovered[i] == FALSE)
            dfs(g,i); // push(&sorted,i) when processed

    print_stack(&sorted);      /* report topological order */
}
```

# Topological Sorting



A DAG with only one topological sort ( $G, A, B, C, F, E, D$ )

```

DFS(g,A) -> DFS(g,B) -> DFS(g,C) -> DFS(g,E) -> DFS(g,D) -> Push(D)
                                     Push(E)
                                     -> DFS(g,F)   Push(F)
                                     Push(C)
  
```

Push(B)

Push(A)

DFS(g,G) -> Push(G)

Order of discovery: A, B, C, E, D, F, G

Order of processing: D, E, F, C, B, A, G

Stack:

G  
A  
B  
C  
F  
E  
D

Topological Sort: G, A, B, C, F, E, D