

04-630

Data Structures and Algorithms for Engineers

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Lecture 21

Graphs

- Types of graph
- Adjacency matrix representation
- Adjacency list representation
- Breadth-First Search traversal
- Depth-First Search traversal
- Topological Sorting
- Minimum Spanning Tree
 - Prim's algorithm
 - Kruskal's algorithm
- Shortest Path Algorithms
 - Dijkstra's algorithm
 - Floyd's algorithm

Minimum Spanning Tree

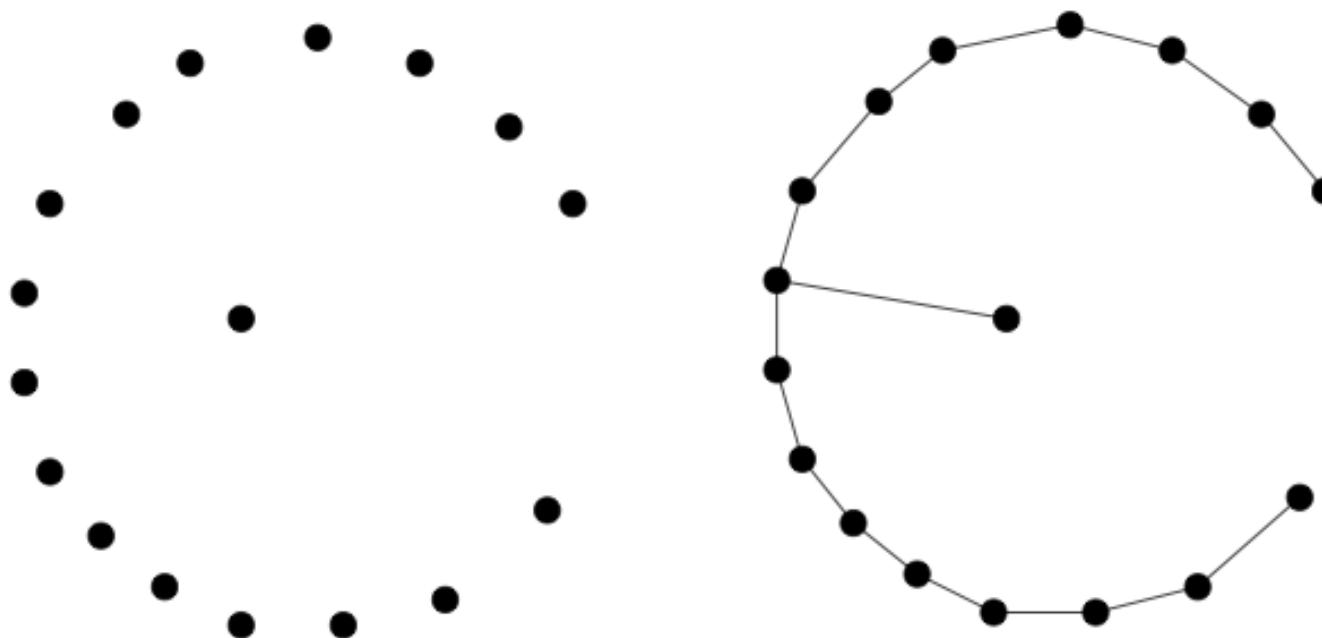
- A **spanning tree** of a graph $G = (V, E)$ is a subset of edges from E forming a tree connecting all vertices of V
- For edge-weighted graphs we are interested in the **minimum spanning tree**:
 - The tree whose sum of edge weights is as small as possible

Minimum Spanning Tree

Example application:

- find the smallest amount of a connector (road, wire, pipe) required to connect a set of points (cities, houses, components)

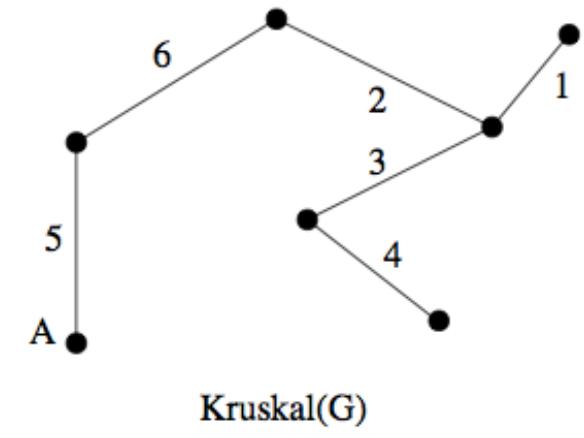
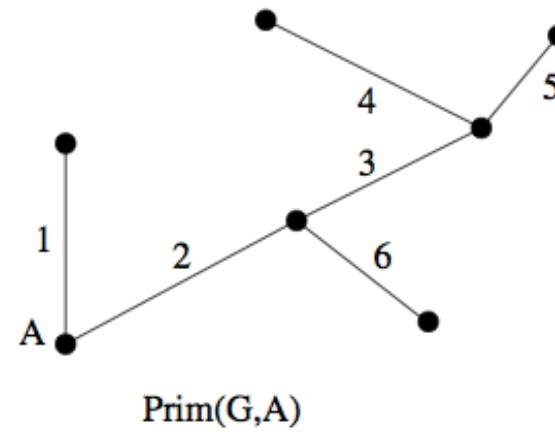
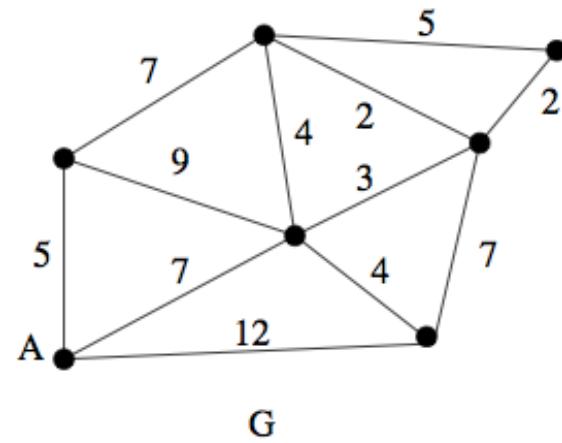
Minimum Spanning Tree



Minimum Spanning Tree

- A minimum spanning tree minimizes the total length (weight) over all possible spanning trees
- There can be more than one minimum spanning tree in a graph
- Two main algorithms
 - Prim's Algorithm
 - Kruskal's Algorithm

Minimum Spanning Tree



Numbers denote order of insertion

Minimum Spanning Tree

Prim's Algorithm

- Greedy algorithmic strategy:

Make a decision about what to do next by selecting the best **local** option from all available choices without regard to **global** structure,

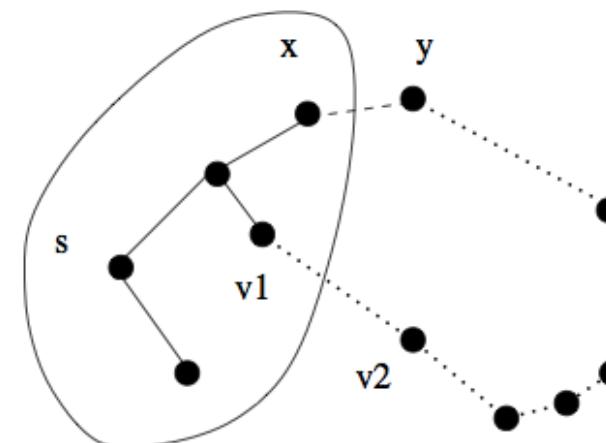
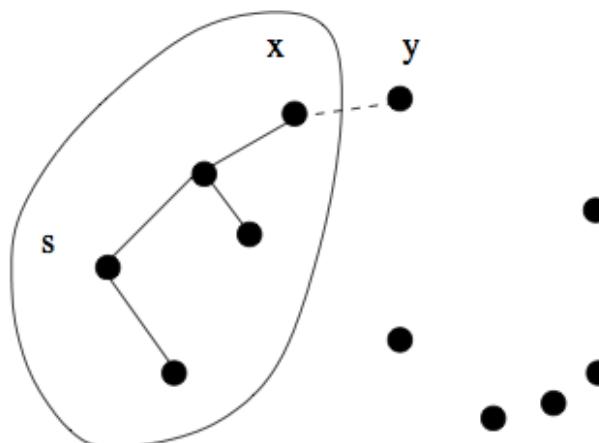
do it,

and then repeat until finished

Minimum Spanning Tree

Prim's Algorithm

- Repeatedly select the **smallest weight edge** that will enlarge the number of vertices in the tree
 - Start from one (any) vertex,
 - Grow the rest of the tree, one edge at a time,
 - Until all vertices are included



Minimum Spanning Tree

Prim's Algorithm

Prim-MST(G):

Select an arbitrary vertex s to start the tree from

While (there are still non-tree vertices remaining)

 Select the edge of minimum weight between
 a tree & non-tree vertex

 Add the selected edge and vertex to the tree T_{prim}

Minimum Spanning Tree

```
/* Prim's algorithm */  
  
prim(graph *g, int start) {  
    int i;                      /* counter */  
    edgenode *p;                /* temporary pointer */  
    bool intree[MAXV+1];        /* is the vertex in the tree yet? */  
    int distance[MAXV+1];       /* cost of adding to tree */  
    int parent[MAXV+1];         /* parent vertex */  
    int v;                      /* current vertex to process */  
    int w;                      /* candidate next vertex */  
    int weight;                 /* edge weight */  
    int dist;                   /* best current distance from start */  
  
    for (i=1; i<=g->nvertices; i++) {  
        intree[i] = FALSE;  
        distance[i] = MAXINT;  
        parent[i] = -1;  
    }  
  
    distance[start] = 0;  
    v = start;
```

Minimum Spanning Tree

```
while (intree[v] == FALSE) { // keep going until all vertices
    intree[v] = TRUE;           // are in the tree
    p = g->edges[v];
    while (p != NULL) {        // compute the distances and parents
        w = p->y;
        weight = p->weight;
        if ((weight < distance[w]) && (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }
    v = 1;
    dist = MAXINT;             // find the vertex with
    for (i=1; i<=g->nvertices; i++) // the minimum distance
        if ((intree[i] == FALSE) && (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
    }
}
```

Minimum Spanning Tree

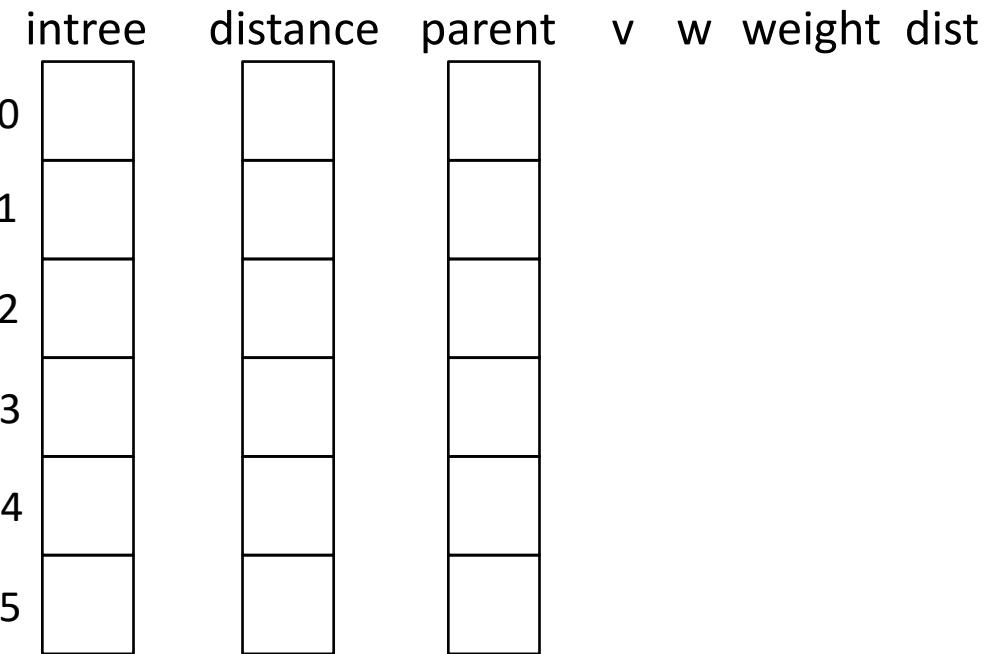
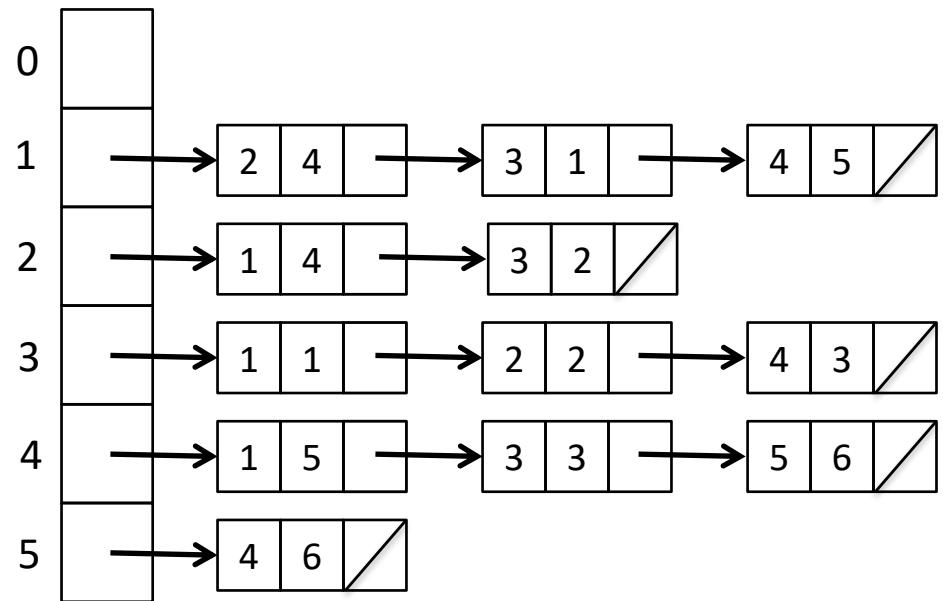
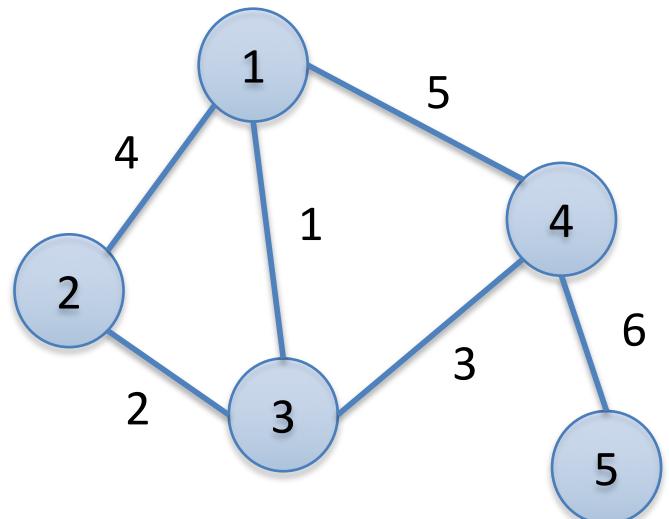
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    intree[v] = TRUE;           // are in the tree
    p = g->edges[v];
    while (p != NULL) {         // compute the distances and parents
        w = p->y;
        weight = p->weight;
        if ((weight < distance[w]) && (intree[w] == FALSE)) {
            distance[w] = weight;
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        }
        p = p->next;
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    dist = MAXINT;                // find the vertex with
    for (i=1; i<=g->nvertices; i++) // the minimum distance
        if ((intree[i] == FALSE) && (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
    }
}

Find the weights of all edges from v
```

Minimum Spanning Tree

```
while (intree[v] == FALSE) { // keep going until all vertices
    intree[v] = TRUE;           // are in the tree
    p = g->edges[v];
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        w = p->y;
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            distance[w] = weight;
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        }
        p = p->next;
    }
    v = 1;
    dist = MAXINT; // find the vertex with the minimum weight
    for (i=1; i<=g->nvertices; i++) // the minimum distance
        if ((intree[i] == FALSE) && (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}
```

Find the minimum weight... this gives the vertex to be added to the MST



```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

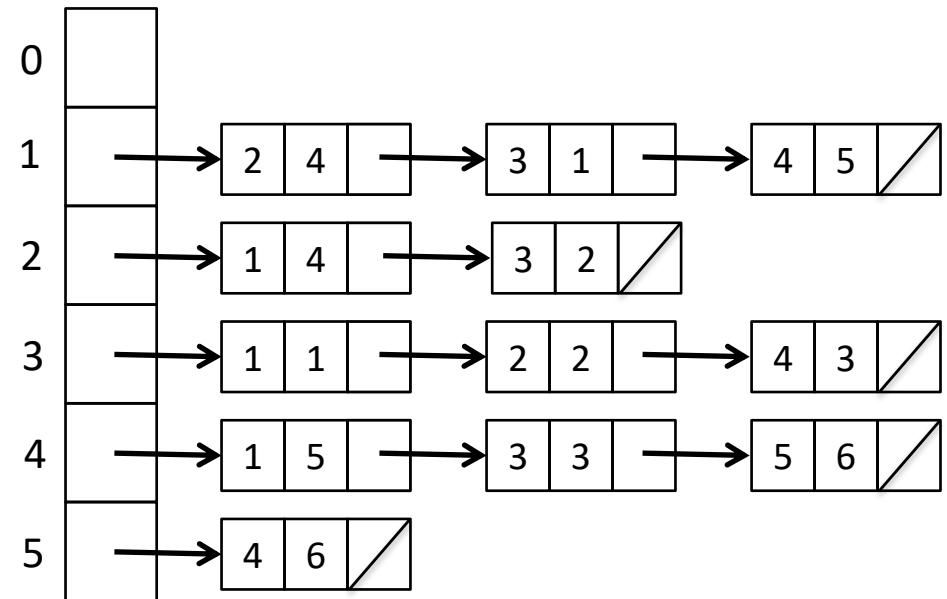
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        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0							
1							
2							
3							
4							
5							

```

for (i=1; i<=g->nvertices; i++) {
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distance[start] = 0;
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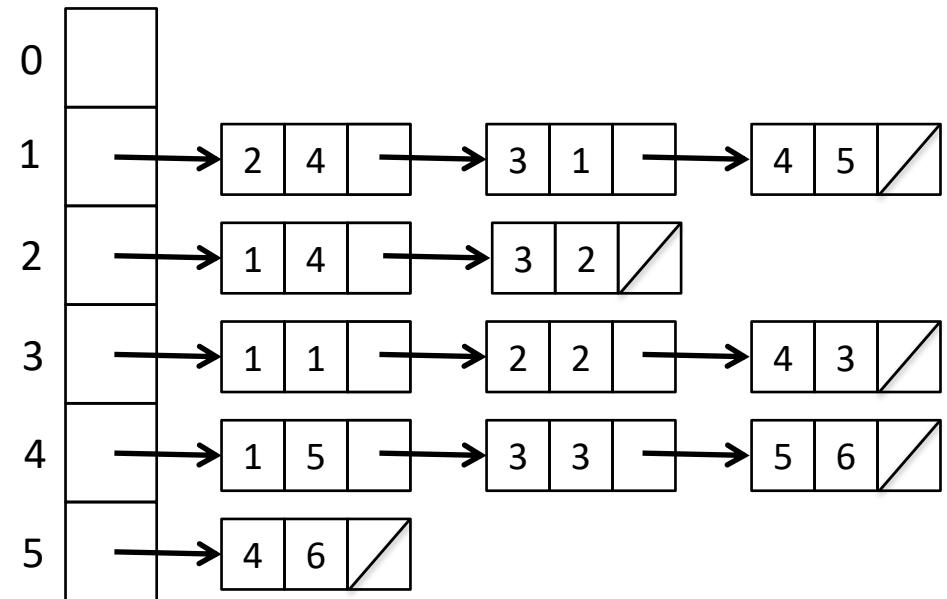
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    for (i=1; i<=g->nvertices; i++)
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}

```



	intree	distance	parent	v	w	weight	dist
0							
1	F	∞	-1				
2	F	∞	-1				
3	F	∞	-1				
4	F	∞	-1				
5	F	∞	-1				

```

for (i=1; i<=g->nvertices; i++) {
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distance[start] = 0;
v = start;

while (intree[v] == FALSE) {

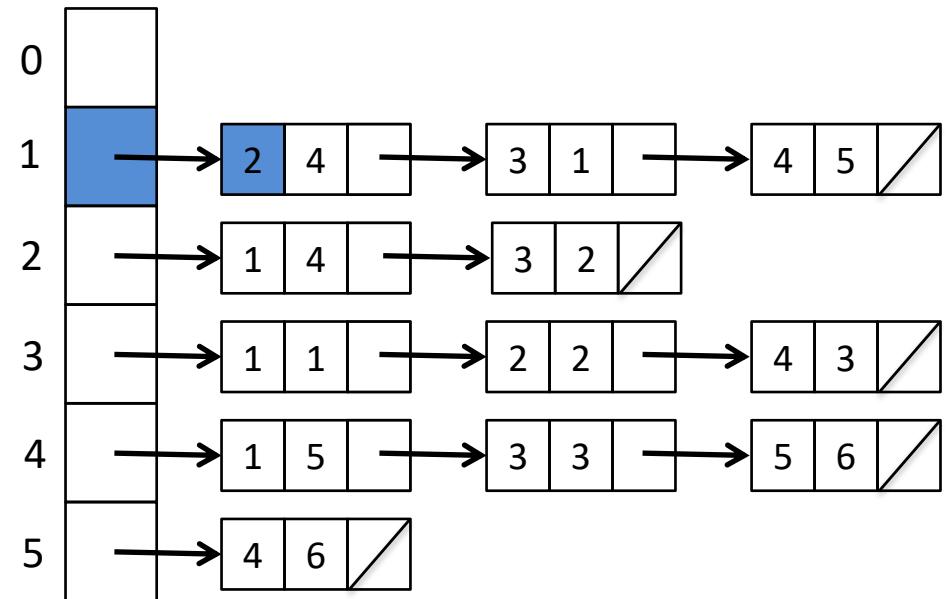
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            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0				1	2	4	
1	T	0	-1				
2	F	∞	-1				
3	F	∞	-1				
4	F	∞	-1				
5	F	∞	-1				

```

for (i=1; i<=g->nvertices; i++) {
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}

distance[start] = 0;
v = start;

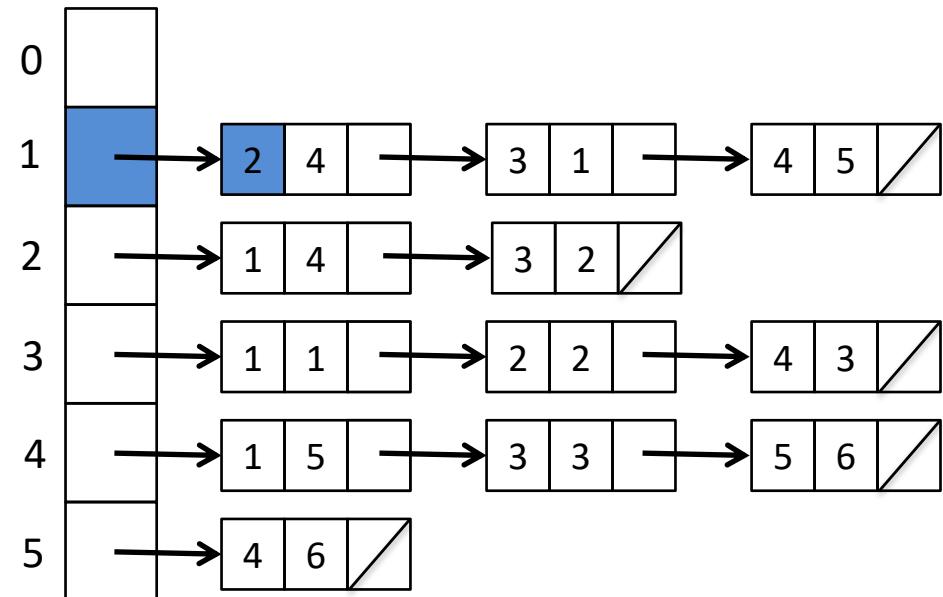
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        }
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}

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2	F	4	1				
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4	F	∞	-1				
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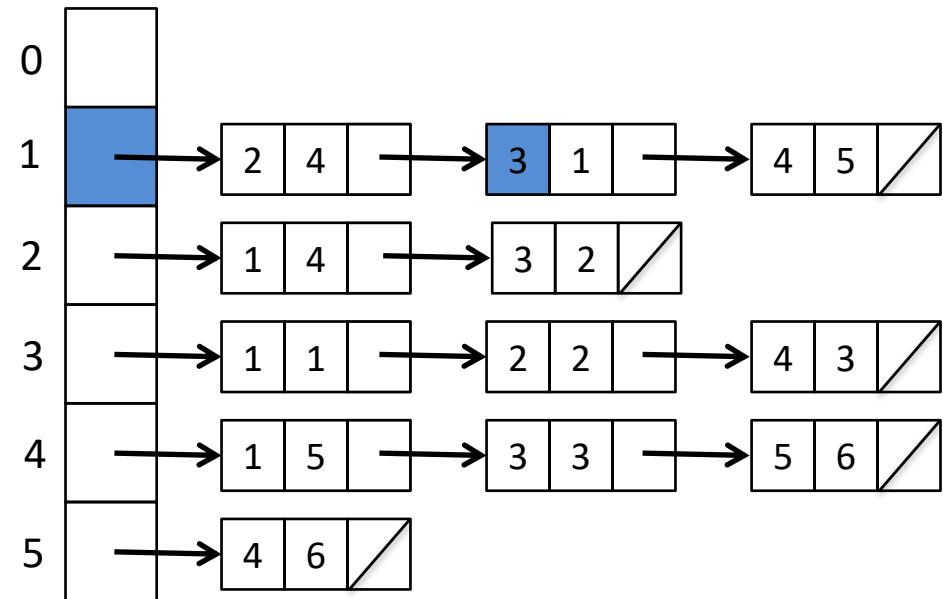
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```



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0				1	2	4	
1	T	0	-1		3	1	
2	F	4	1				
3	F	1	1				
4	F	∞	-1				
5	F	∞	-1				

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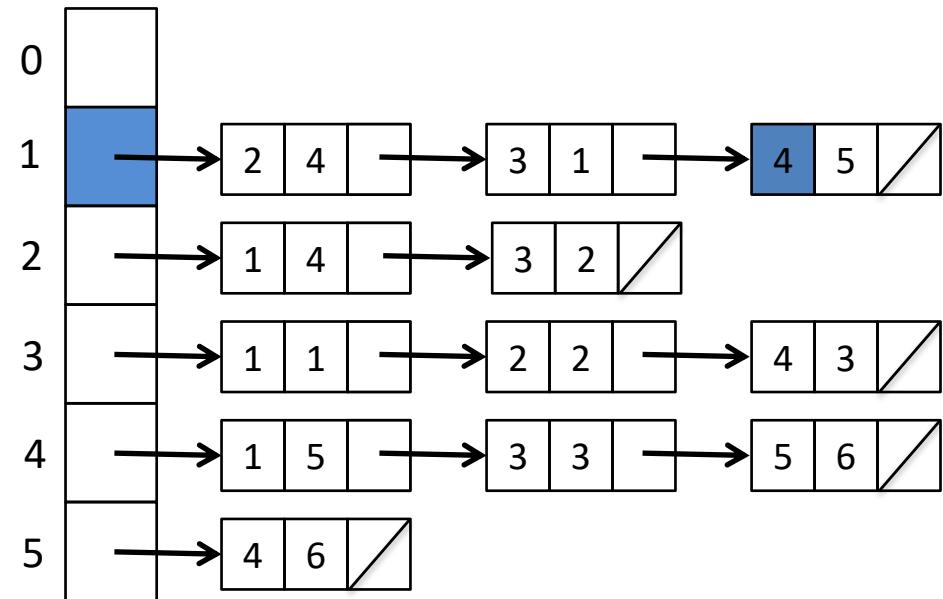
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}

```



	intree	distance	parent	v	w	weight	dist
0	-	-	-	1	2	4	
1	T	0	-1	3	1		
2	F	4	1	4	5		
3	F	1	1				
4	F	5	1				
5	F	∞	-1				

```

for (i=1; i<=g->nvertices; i++) {
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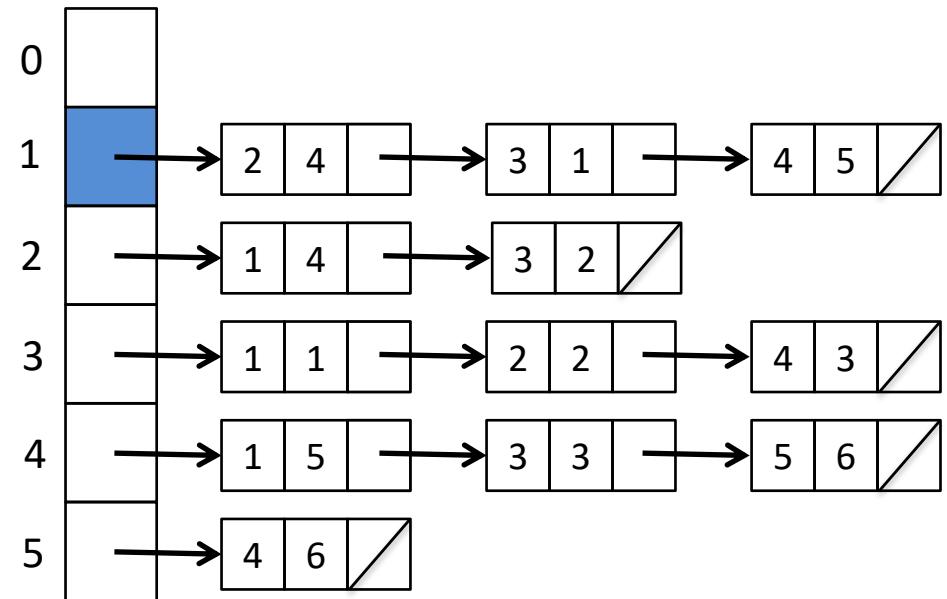
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```



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2	F	4	1	1	3	1	4
3	F	1	1	2	4	5	1
4	F	5	1	3			
5	F	∞	-1				

```

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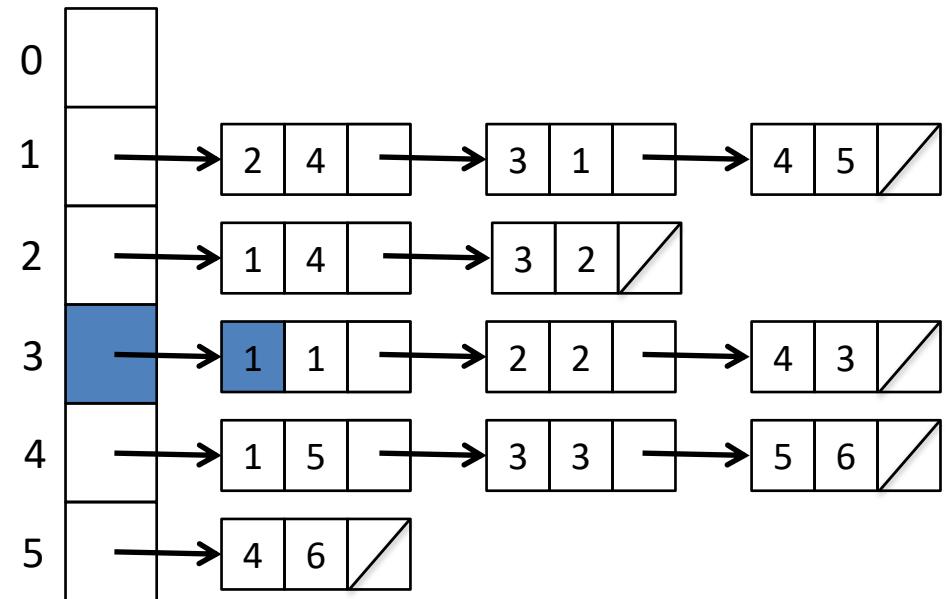
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    for (i=1; i<=g->nvertices; i++)
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```



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1	T	0	-1	1	2	4	4
2	F	4	1	2	4	5	1
3	T	1	1	3	1	1	1
4	F	5	1				
5	F	∞	-1				

```

for (i=1; i<=g->nvertices; i++) {
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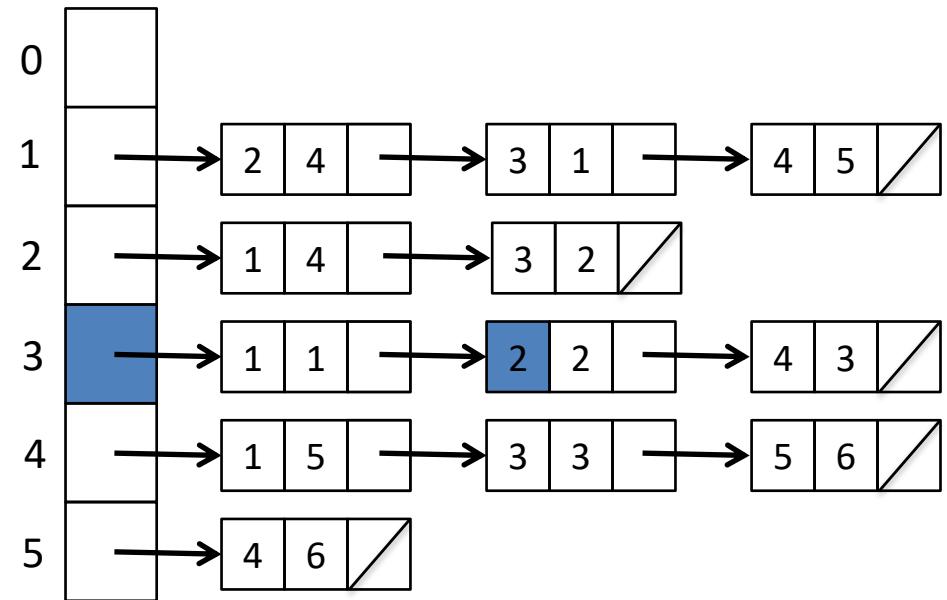
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5	F	∞	-1				

```

for (i=1; i<=g->nvertices; i++) {
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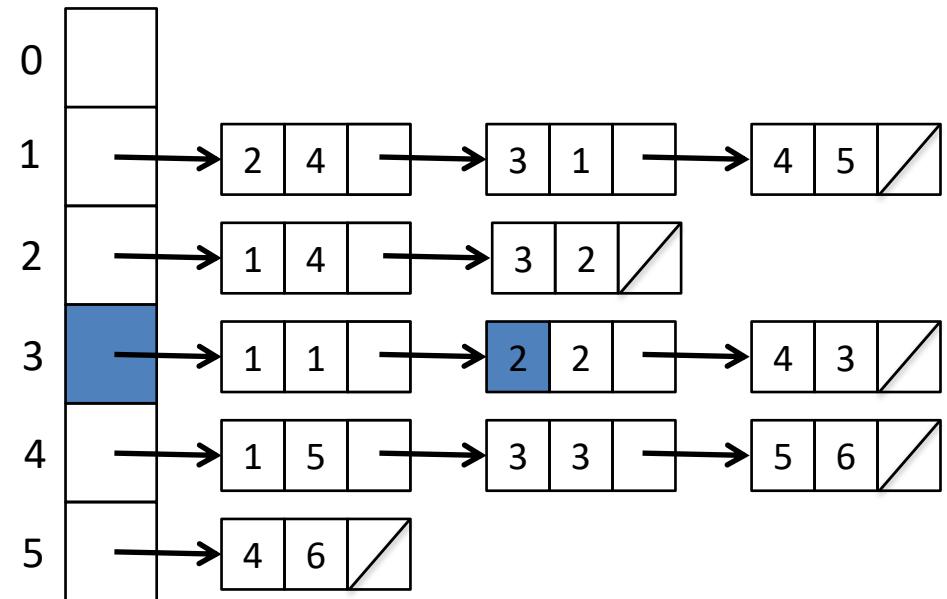
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```



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```

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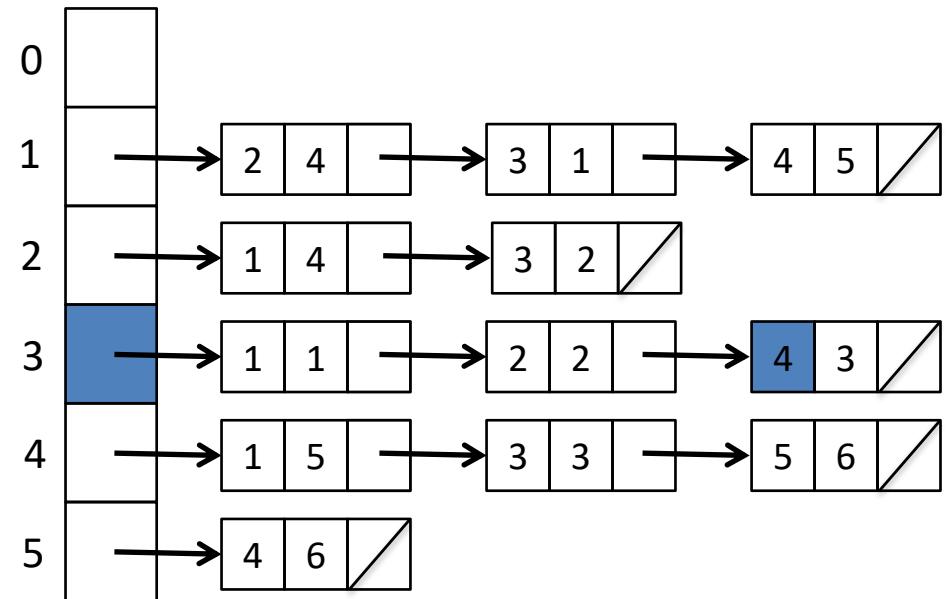
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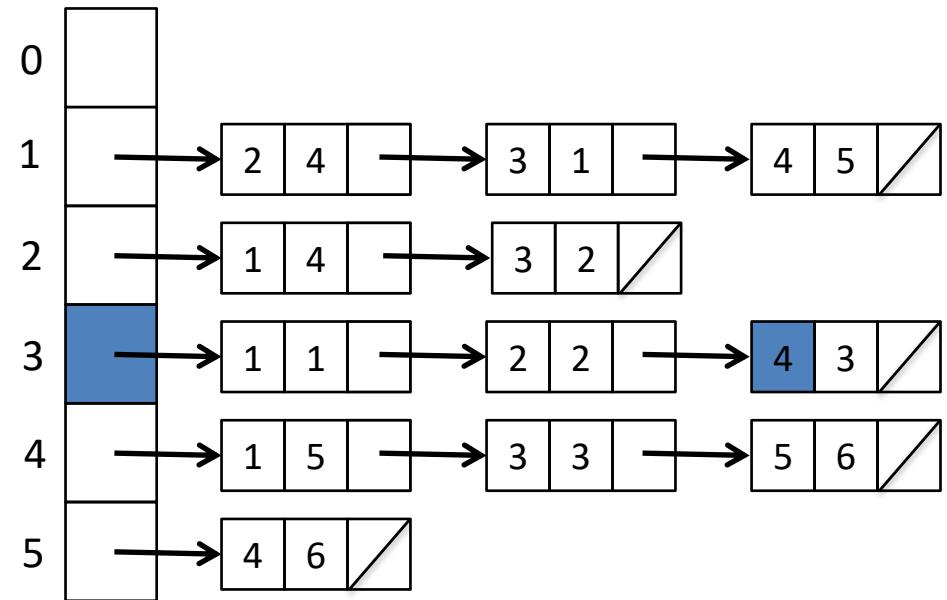
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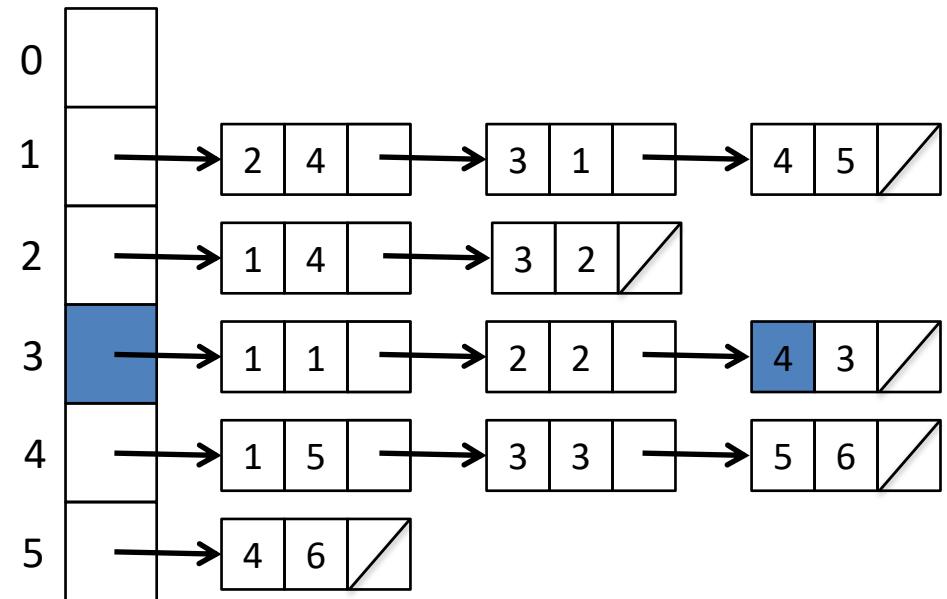
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        weight = p->weight;
        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0							∞
1	T	0	-1	1	2	4	4
2	F	2	3	1	3	1	1
3	T	1	1	2	4	5	2
4	F	3	3	3	1	1	3
5	F	∞	-1				

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

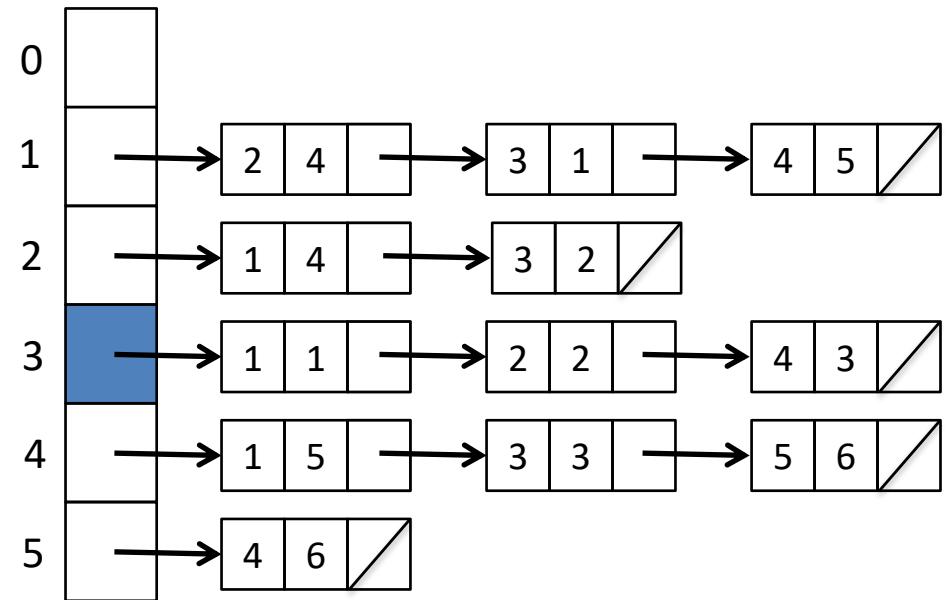
while (intree[v] == FALSE) {

    intree[v] = TRUE;
    p = g->edges[v];

    while (p != NULL) {
        w = p->y;
        weight = p->weight;
        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0							∞
1	T	0	-1	1	2	4	4
2	F	2	3	1	3	1	∞
3	T	1	1	2	4	3	2
4	F	3	3				
5	F	∞	-1				

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

while (intree[v] == FALSE) {

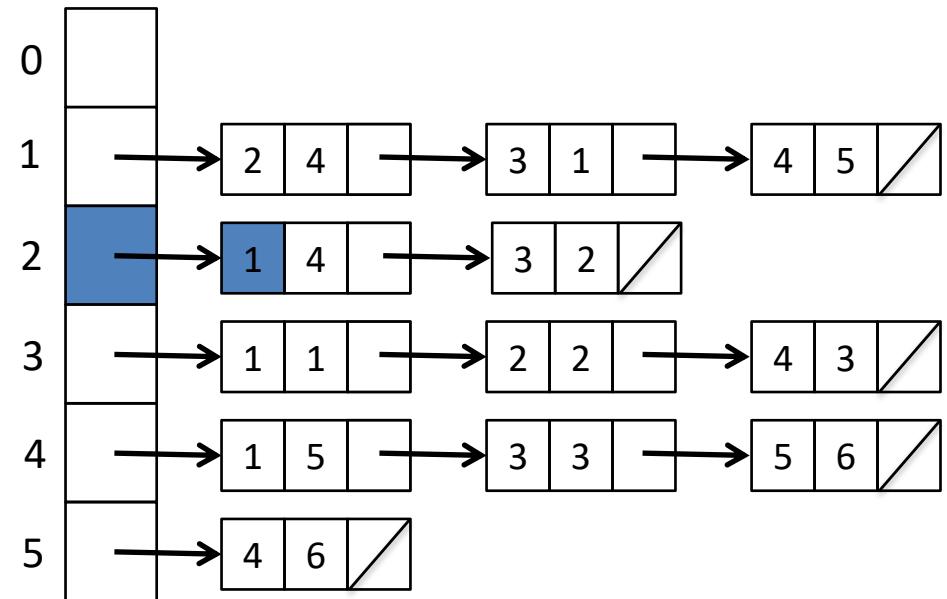
    intree[v] = TRUE;
    p = g->edges[v];

    while (p != NULL) {
        w = p->y;
        weight = p->weight;

        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0							∞
1	T	0	-1	1	2	4	4
2	T	2	3	1	3	1	∞
3	T	1	1	2	4	3	2
4	F	3	3	1			4
5	F	∞	-1				

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

while (intree[v] == FALSE) {

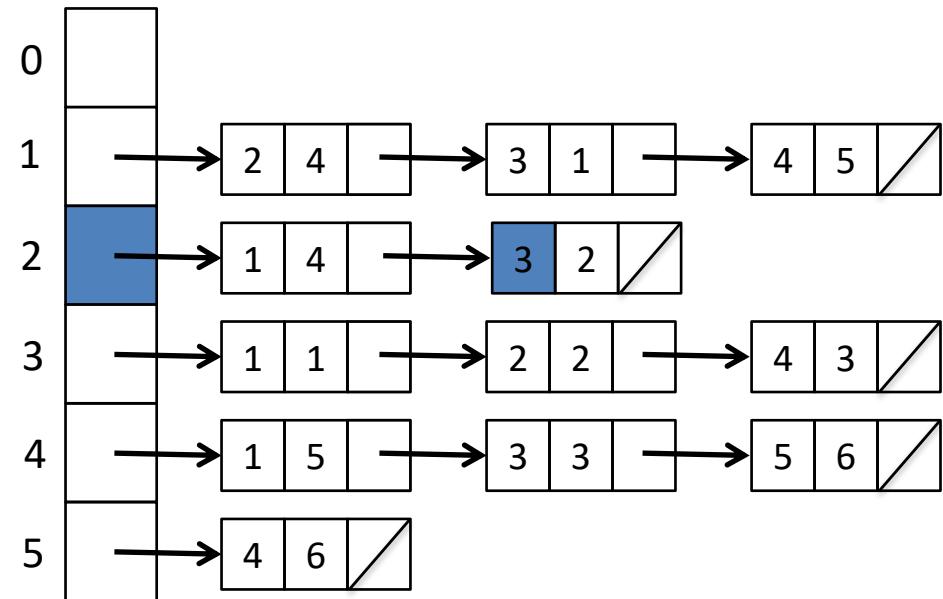
    intree[v] = TRUE;
    p = g->edges[v];

    while (p != NULL) {
        w = p->y;
        weight = p->weight;

        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0							∞
1	T	0	-1	1	2	4	4
2	T	2	3	1	3	1	∞
3	T	1	1	2	4	3	2
4	F	3	3	1			4
5	F	∞	-1	3	2		

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

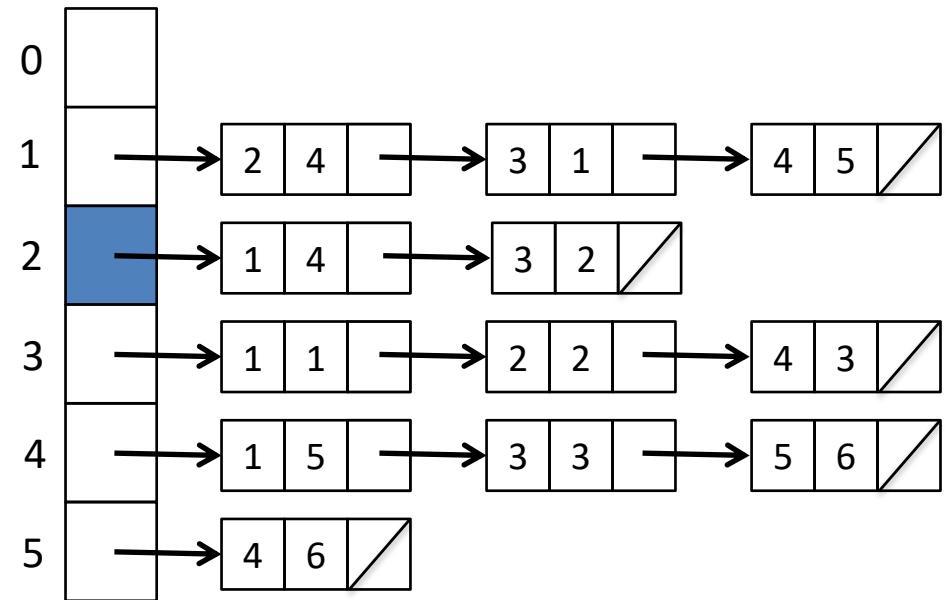
while (intree[v] == FALSE) {

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    p = g->edges[v];

    while (p != NULL) {
        w = p->y;
        weight = p->weight;
        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0							∞
1	T	0	-1	1	2	4	4
2	T	2	3	1	3	1	1
3	T	1	1	2	4	3	∞
4	F	3	3	1	1	4	3
5	F	∞	-1	4	3	2	

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

while (intree[v] == FALSE) {

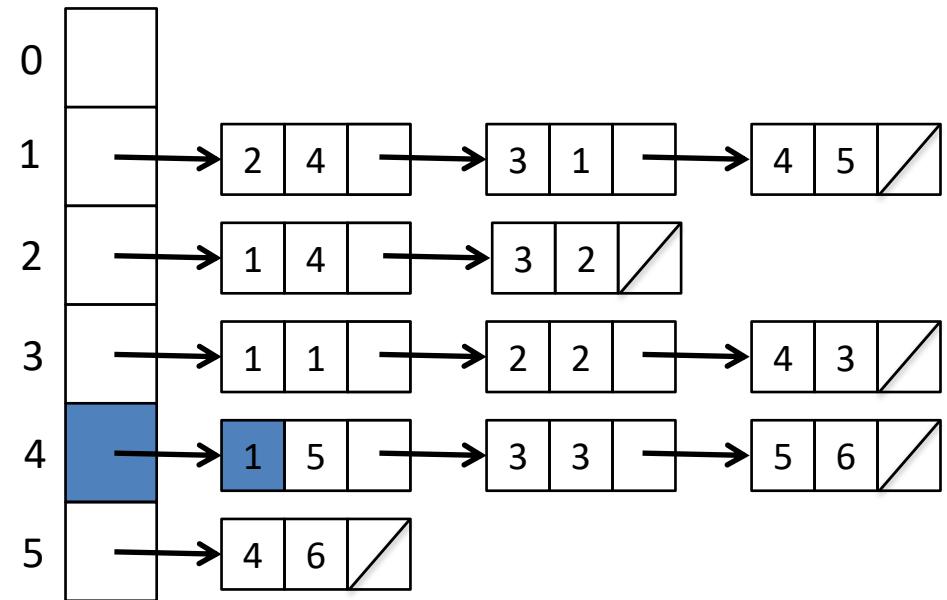
    intree[v] = TRUE;
    p = g->edges[v];

    while (p != NULL) {
        w = p->y;
        weight = p->weight;

        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0							
1	T	0	-1	1	2	4	∞
2	T	2	3	1	3	1	4
3	T	1	1	2	4	3	∞
4	T	3	3	4	3	2	
5	F	∞	-1	1		5	

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

while (intree[v] == FALSE) {

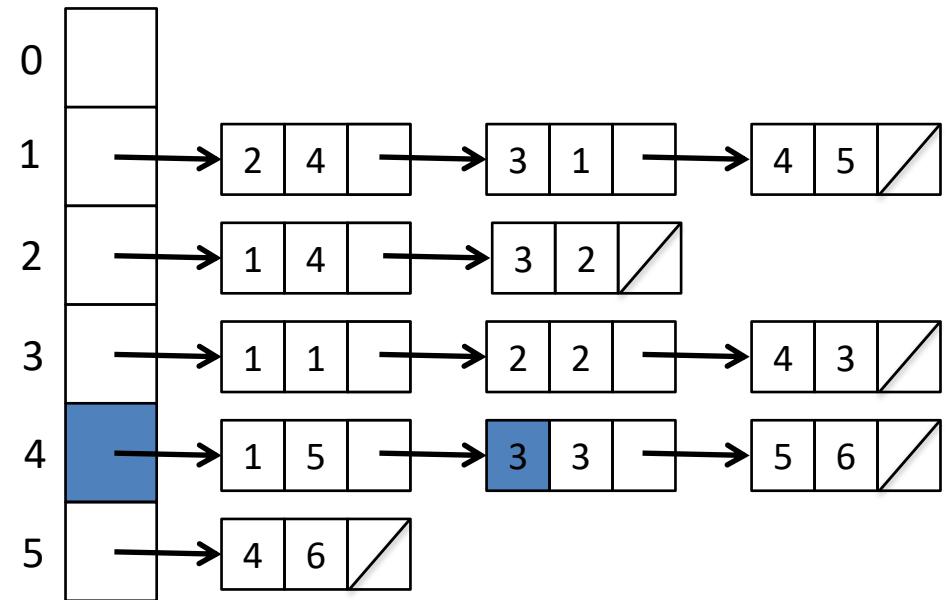
    intree[v] = TRUE;
    p = g->edges[v];

    while (p != NULL) {
        w = p->y;
        weight = p->weight;

        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
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```



	intree	distance	parent	v	w	weight	dist
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1	T	0	-1	1	2	4	∞
2	T	2	3	1	3	1	4
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4	T	3	3	4	3	2	
5	F	∞	-1	1	1	5	

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

while (intree[v] == FALSE) {

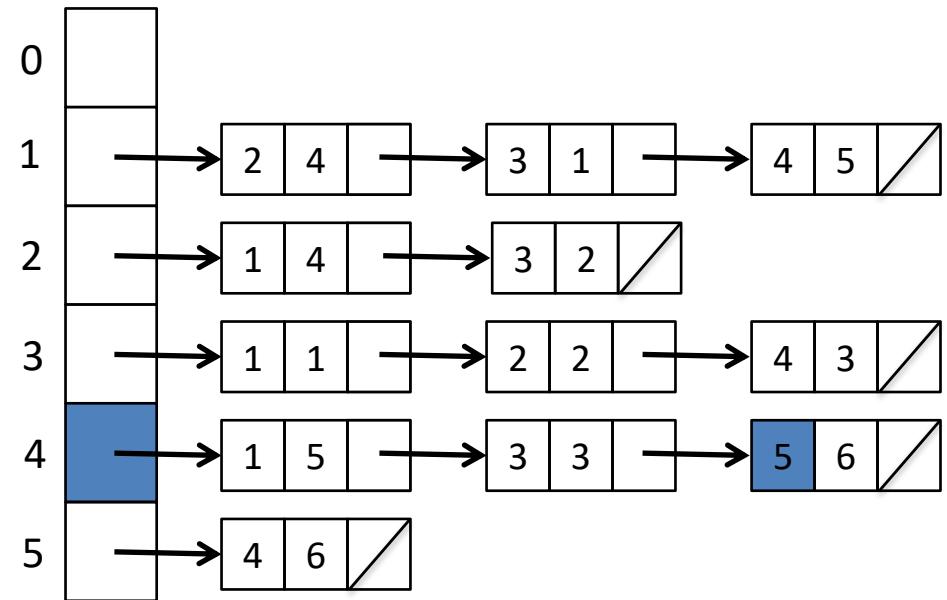
    intree[v] = TRUE;
    p = g->edges[v];

    while (p != NULL) {
        w = p->y;
        weight = p->weight;

        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
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1	T	0	-1	1	2	4	∞
2	T	2	3	1	3	1	4
3	T	1	1	2	4	3	∞
4	T	3	3	4	3	2	
5	F	∞	-1	1	5		

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

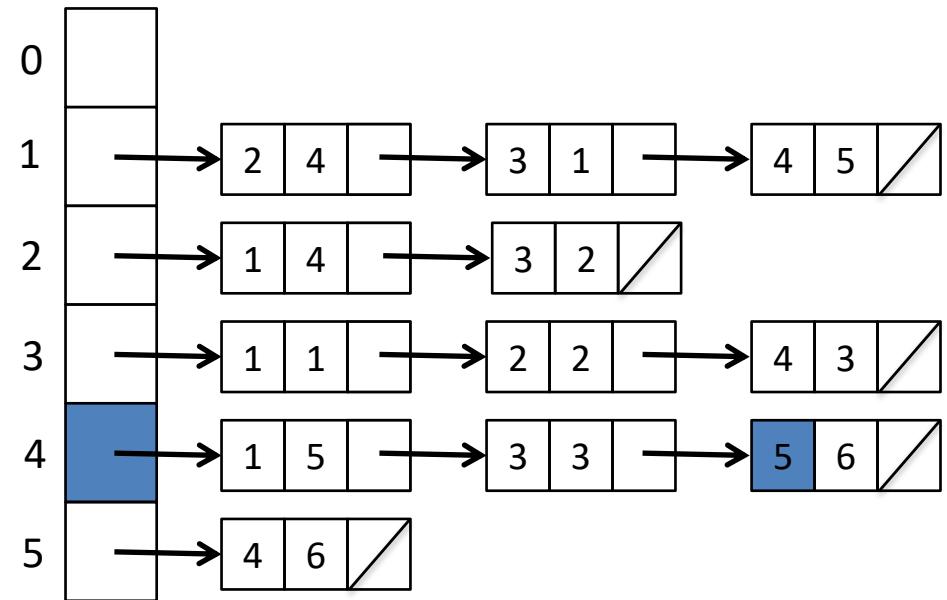
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    while (p != NULL) {
        w = p->y;
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            (intree[w] == FALSE)) {
            distance[w] = weight;
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        }
        p = p->next;
    }

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    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0							
1	T	0	-1	1	2	4	∞
2	T	2	3	1	3	1	4
3	T	1	1	2	4	3	∞
4	T	3	3	4	3	2	
5	F	6	4	1	5		

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

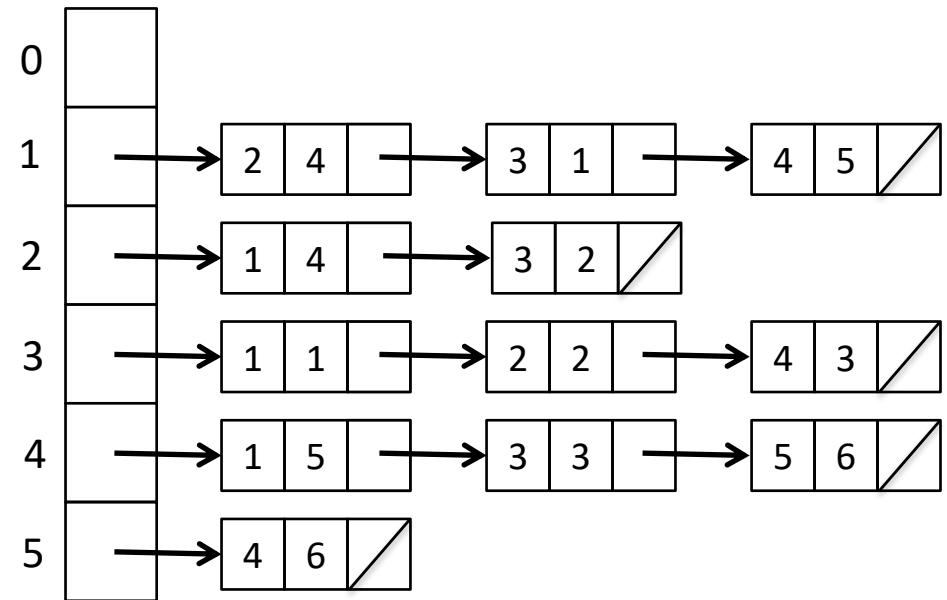
while (intree[v] == FALSE) {

    intree[v] = TRUE;
    p = g->edges[v];

    while (p != NULL) {
        w = p->y;
        weight = p->weight;
        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
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    v = 1;
    dist = MAXINT;
    for (i=1; i<=g->nvertices; i++)
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            dist = distance[i];
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}

```



	intree	distance	parent	v	w	weight	dist
0							∞
1	T	0	-1	2	4	5	4
2	T	2	3	1	2	2	2
3	T	1	1	2	4	3	∞
4	T	3	3	4	3	2	∞
5	F	6	4	1	1	5	6

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
    distance[i] = MAXINT;
    parent[i] = -1;
}

distance[start] = 0;
v = start;

while (intree[v] == FALSE) {

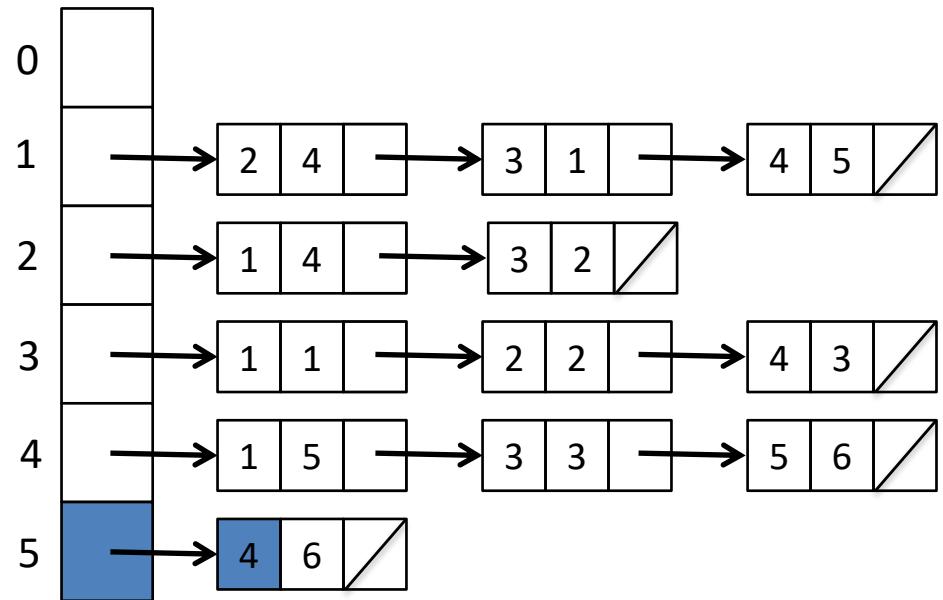
    intree[v] = TRUE;
    p = g->edges[v];

    while (p != NULL) {
        w = p->y;
        weight = p->weight;

        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
    }

    v = 1;
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    for (i=1; i<=g->nvertices; i++)
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            (distance[i] < dist)) {
            dist = distance[i];
            v = i;
        }
}

```



	intree	distance	parent	v	w	weight	dist
0				1	∞
1	T	0	-1	1	4	6	4
2	T	2	3	3			1
3	T	1	1	1	2		∞
4	T	3	3	3	4		∞
5	T	6	4	1	5		6

```

for (i=1; i<=g->nvertices; i++) {
    intree[i] = FALSE;
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}

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v = start;

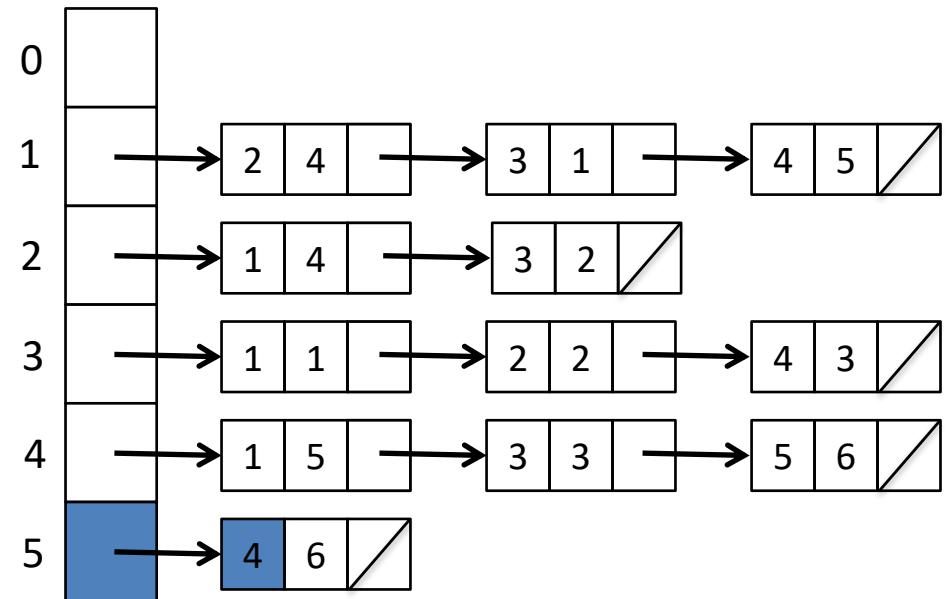
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    p = g->edges[v];

    while (p != NULL) {
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        weight = p->weight;
        if ((weight < distance[w]) &&
            (intree[w] == FALSE)) {
            distance[w] = weight;
            parent[w] = v;
        }
        p = p->next;
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    for (i=1; i<=g->nvertices; i++)
        if ((intree[i] == FALSE) &&
            (distance[i] < dist)) {
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            v = i;
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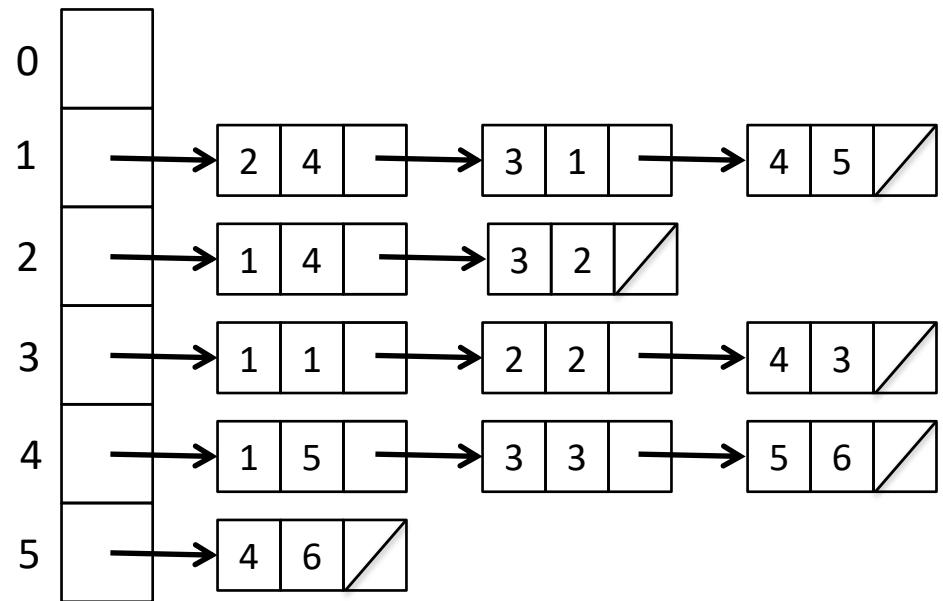
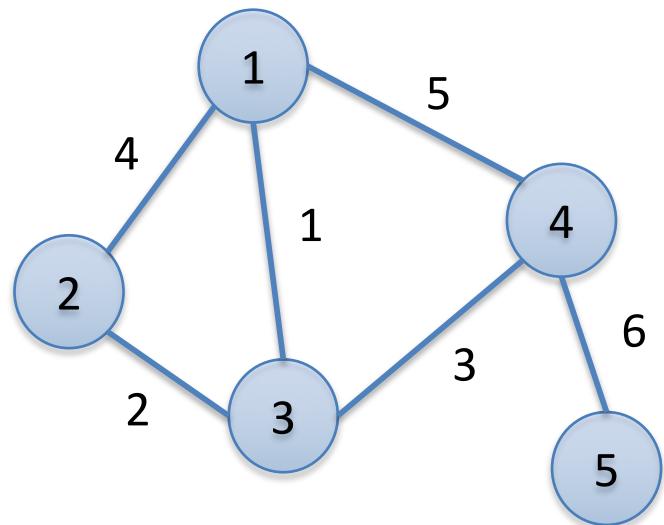
```



	intree	distance	parent	v	w	weight	dist
0				1	∞
1	T	0	-1	1	4	6	4
2	T	2	3	2			1
3	T	1	1	2			∞
4	T	3	3	4			∞
5	T	6	4	1	5	6	6

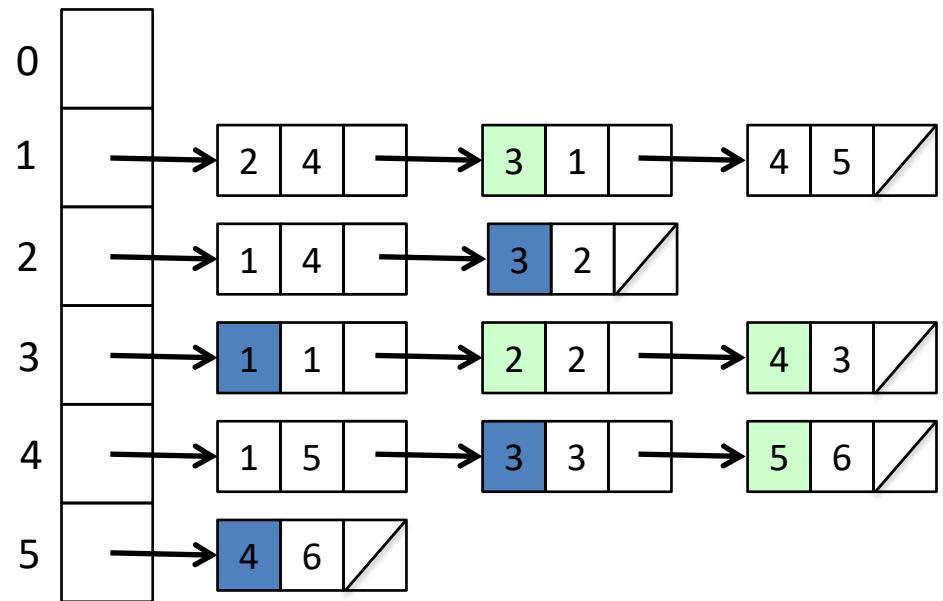
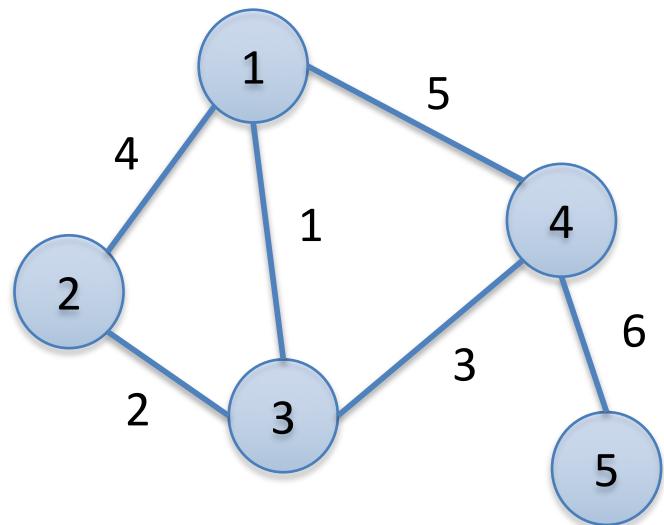
Minimum Spanning Tree

- Prim's Algorithm
 - The minimum spanning tree itself or its cost has to be reconstructed
 - Augment this procedure with statements that print the edges as they are found or totals the weight of all selected edges
 - Alternatively, the tree topology is given by the `parent` relations and so it can be constructed using the original graph

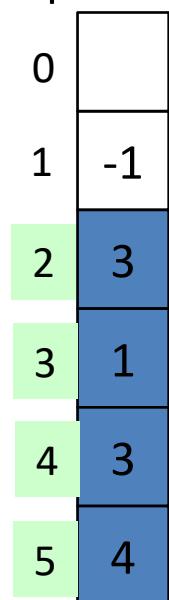


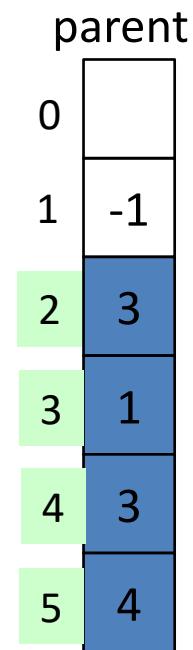
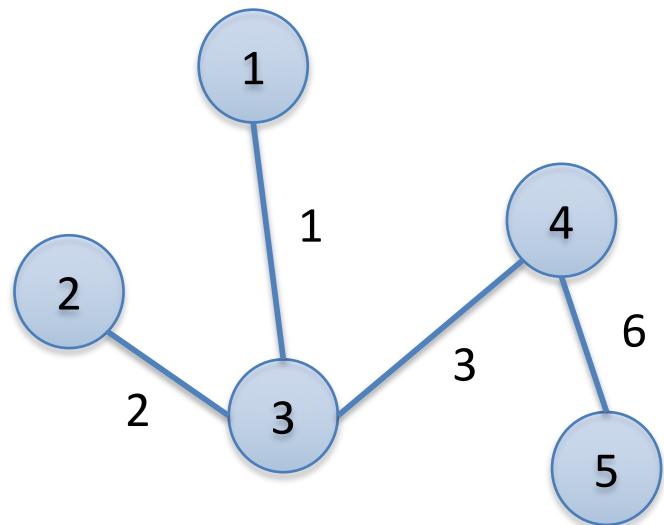
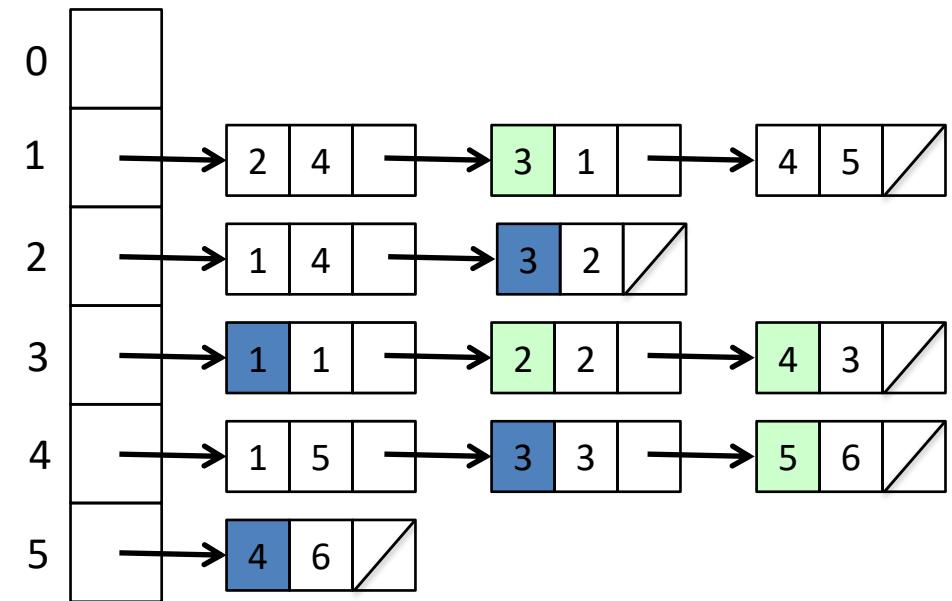
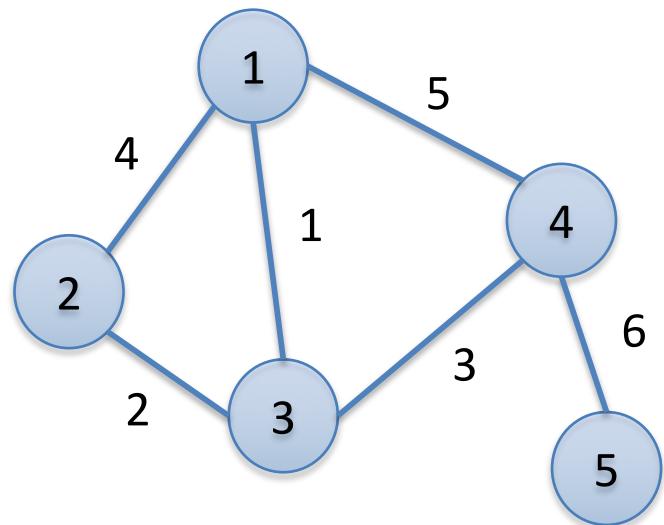
parent

0
-1
3
1
3
4



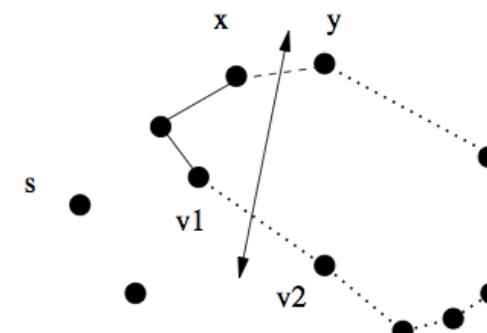
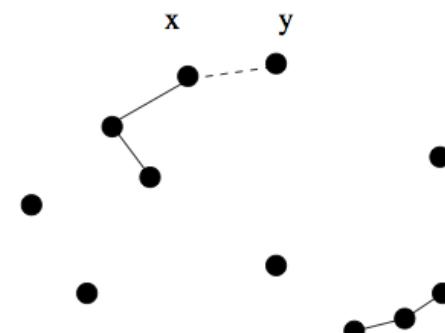
parent





Minimum Spanning Tree

- Kruskal's Algorithm
 - Greedy algorithm:
 - Builds up connected components of vertices, culminating in the MST
 - Initially each vertex forms its own connected component
 - The algorithm repeatedly considers the lightest remaining edge
 - If its two endpoints lie within the same connected component, discard it (because adding it would create a cycle in the tree)
 - Otherwise, insert the edge and merge the two components in to one



Minimum Spanning Tree

- Kruskal's Algorithm

```
Kruskal-MST(G): // note: no start vertex s; cf Prim's Algorithm
```

```
Put the edges in a priority queue ordered by weight  
count = 0  
While (count < n-1) do  
    get next edge (v, w)  
    if (component (v) != component (w))  
        add to T_Kruskal  
        merge component (v) and component (w)
```

Minimum Spanning Tree

- Prim's Algorithm vs. Kruskal's Algorithm
 - Prim $O(mn)$... if we don't keep track of lightest edge
 - Prim $O(n^2)$... if we do but use a simple data structure
 - Prim $O(m + n \log n)$... if we use a priority queue data structure
 - Kruskal $O(m \log m)$
- n vertices, m edges

 - Prim's algorithm is faster on dense graphs (depends on n)
 - Kruskal's algorithm is faster on sparse graphs (depends on m)